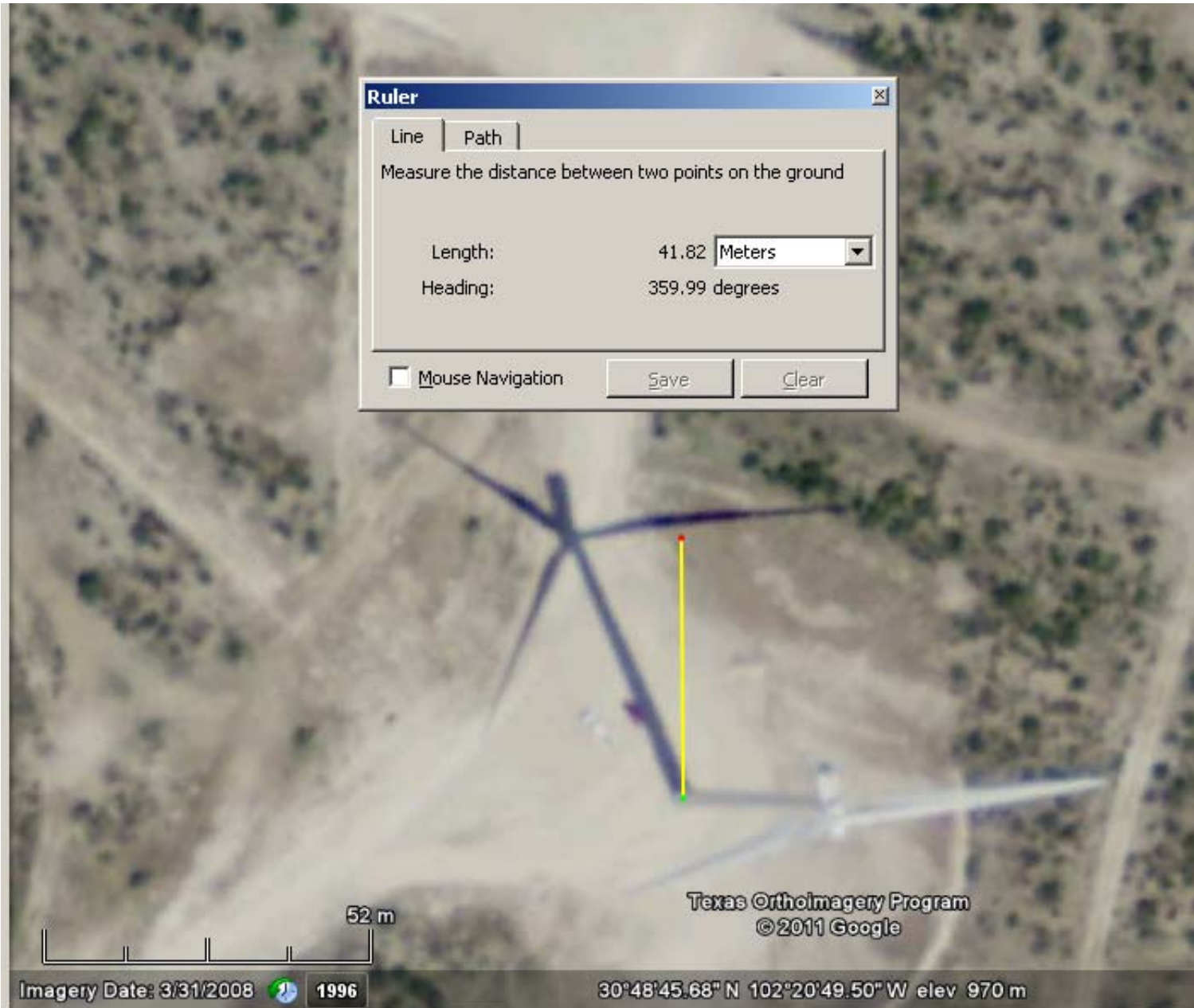
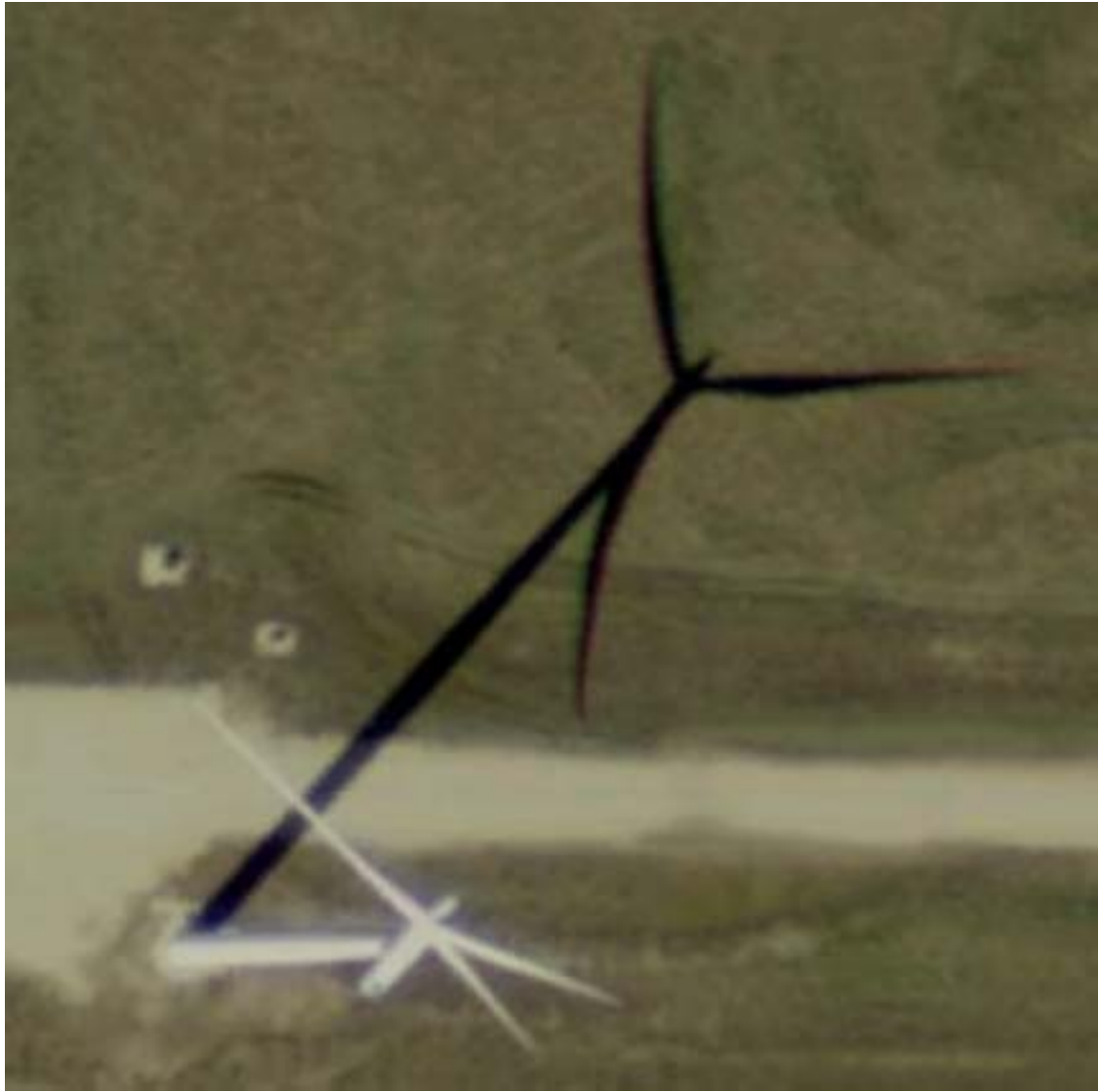


Turbine Spacing. Rows are perpendicular to **prevailing wind direction**.  
Turbines are spaced about 3 top heights apart in the rows, with about 10 top heights between rows.

# Determine My Time of Day, Hub Height and Swept Area and Manufacturer





<b>Specs</b>	GE 1.5sle	GE 1.5xle	GE 2.5	MB 2.4	Comments
Rated Output - MW	1.5	1.5	2.5	2.4	
Rated Wind Speed - m/s	12.5	11.5	12.5	11.5	
Hub Height - m	65	80	85	80	
Rotor Diameter D - m	77	82.5	100	102	
Swept Area - m <sup>2</sup>	4657	5346	7854	8171	
Cut-in Wind Speed - m/s	3.5	3.5	3.0	3.0	
Cut-Out Wind Speed - m/s	25.0	20.0	25.0	25.0	
Rated Blade RPM	20			15	
Blade Length - m				49.7	
Voltage	690			690	
Rated Generator RPM	1200				
<b>Calculations</b>					
Tip Top - m	103.5	121.3	135.0	131.0	
Tip Bottom - m	26.5	38.8	35.0	29.0	
PI * D <sup>2</sup> / 4 - m <sup>2</sup>	4657	5346	7854	8171	
Tip Speed - m/s	81			80	About 80 m/s
Tip Speed Ratio	6.5			7.0	6 to 7
Wind Power Density (KA=KT=1) at Rated Wind Speed - W/m <sup>2</sup>	1196	932	1196	932	About 1 kW/m <sup>2</sup>
Wind Power at Rated Wind Speed - MW	5.6	5.0	9.4	7.6	
Rated Output MW / Wind Power at Rated Speed MW	0.27	0.30	0.27	0.32	About 0.3
Wind Speed(tip top) / Wind Speed (tip bottom), for alpha = 1/7th	1.21	1.18	1.21	1.24	
Wind Speed(tip top) / Wind Speed (tip bottom), for alpha = 0.1	1.15	1.12	1.14	1.16	
Wind Pressure(tip top) / Wind Pressure (tip bottom), for alpha = 1/7th	1.46	1.39	1.46	1.54	
Wind Pressure(tip top) / Wind Pressure (tip bottom), for alpha = 0.1	1.32	1.25	1.30	1.35	About 1.5

<b>Other Comments</b>
1. 100 m tip-top gets you 1.5 MW, 150 m tip-top gets you 2.5 MW. So, MW varies approx. by the square of tip-top height.
2. Required footprint per turbine is 3 tip-top heights perpendicular to prevailing wind direction, and 10 tip-tops in the prevailing wind direction
3. Both footprint and MW vary by the square of tip-top height, and the ratio is about 1.5 MW / 300 / 1000 = 1.5 MW / 0.3 km <sup>2</sup> , which is about 5 MW per km <sup>2</sup> .
4. Conversion factors: 1609 m/mile. 12.5 m/s = 28 mph. 80 m/s = 178 mph.

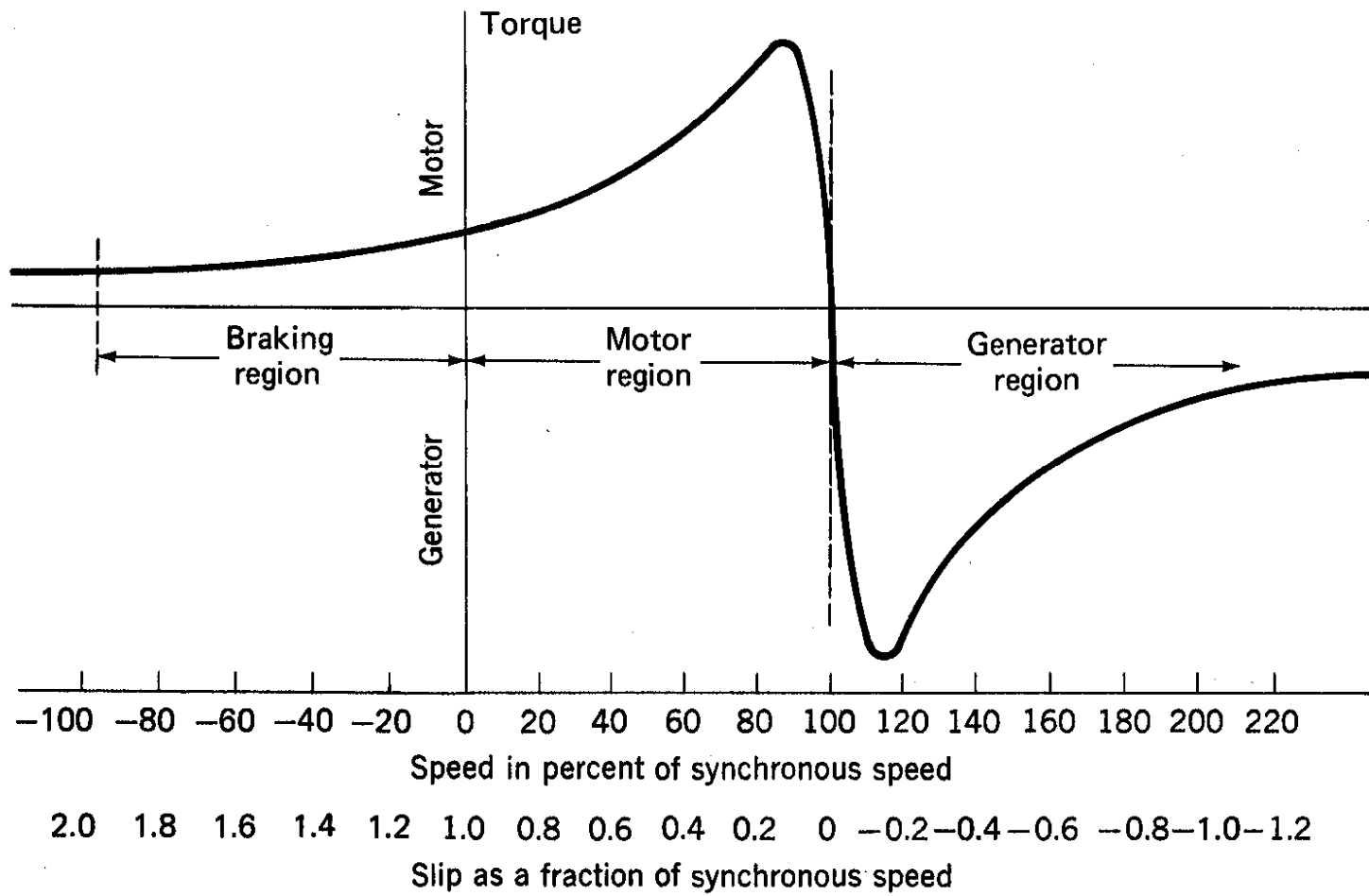


Fig. 9-13. Induction-machine torque-slip curve showing braking, motor, and generator regions.

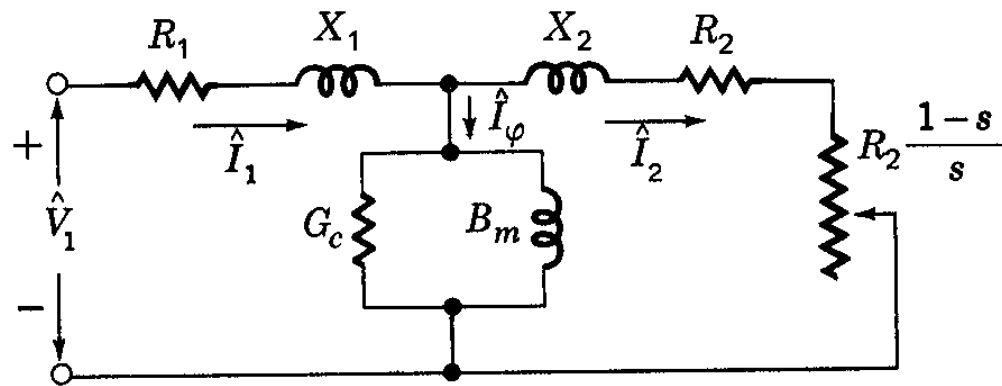


Fig. 9-9. Alternative form of equivalent circuit.

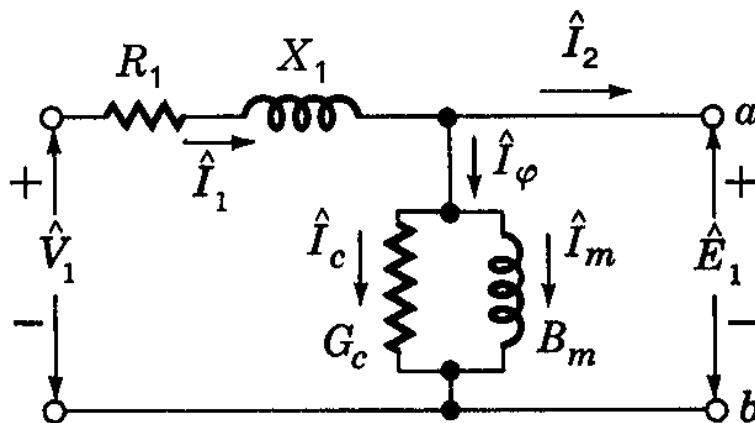
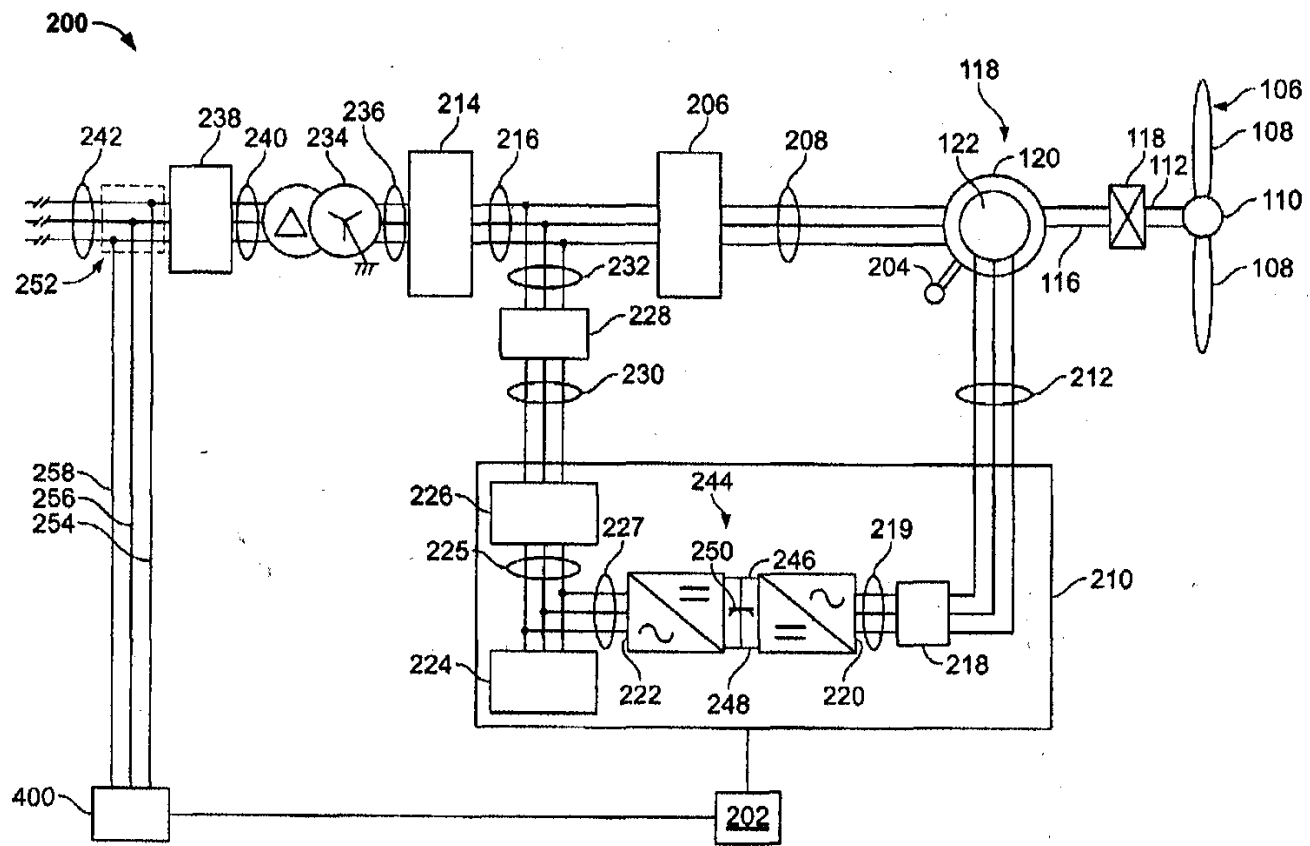
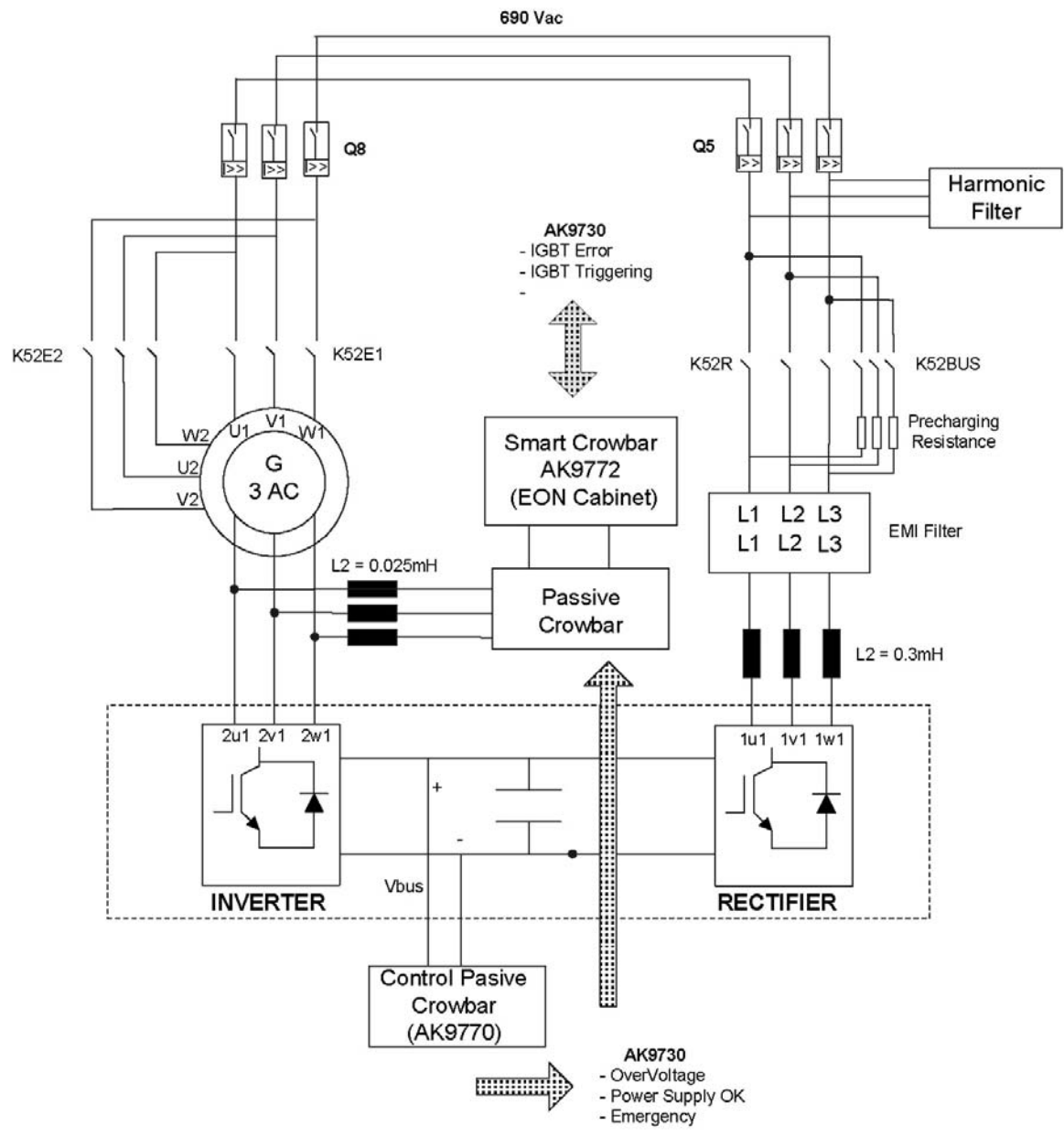


Fig. 9-6. Stator equivalent circuit for a polyphase induction motor.

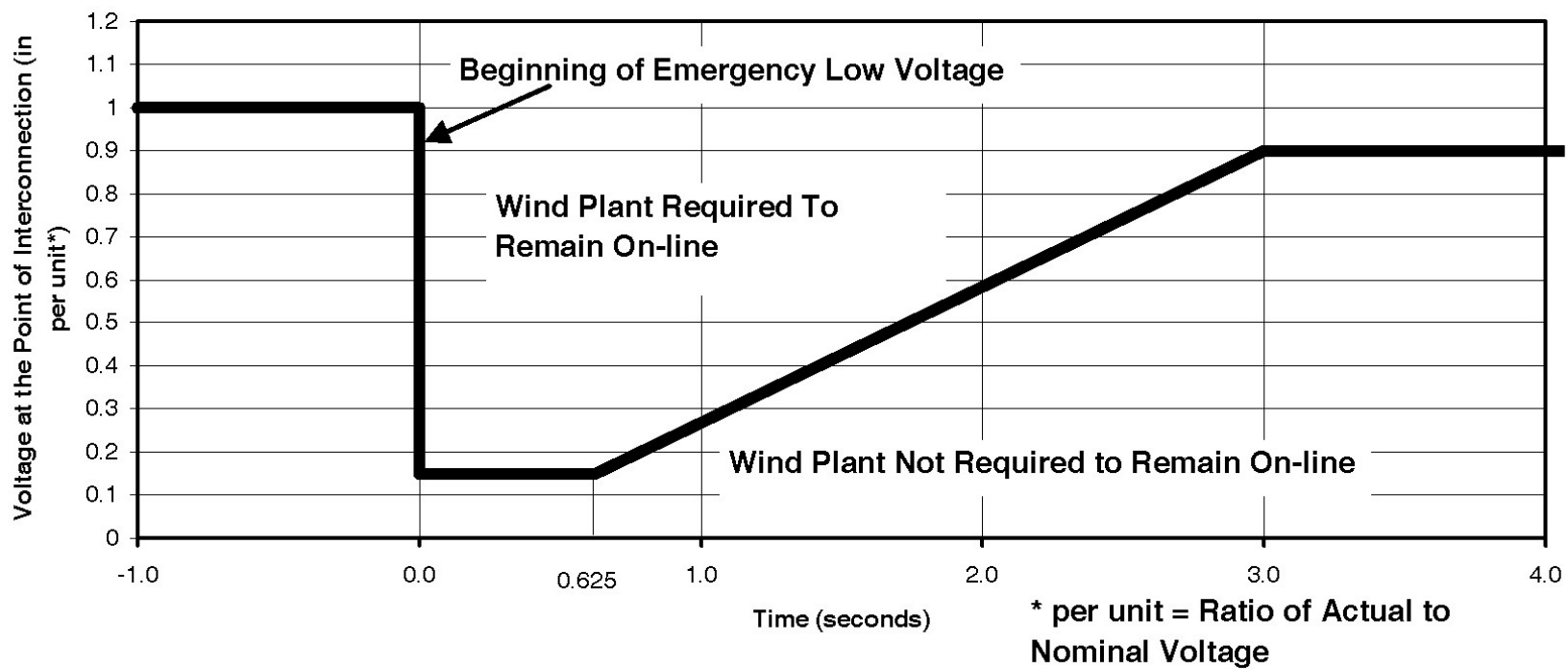






Parameter	Value	Unit
Rated power	1545	KW
Rated voltage	575	V
Apparent Power (@ PF = 0.9 lag)	1717	KVA
Rated frequency	60	Hz
Poles	6	
Power factor - standard	+/- 0.95	
Power factor - optional	+/- 0.90	
Rated current		
Stator (PF = 0.9 lag)	1509	A
Rotor (PF = 0.9 lag)	624	A
Locked rotor voltage	1715	V
Transformation ratio	0.335	
Connection		
Stator	Star or Delta	
Rotor	Star	
Synchronous speed	1200	rpm
Rated speed	1440	rpm
Slip at rated speed	-20	%
Speed range	800 - 1600	rpm
Generator moment of inertia	75	Kg.m <sup>2</sup>
Generator inertia constant	0.55	s
Total moment of inertia (ref to high speed side)	960	Kg.m <sup>2</sup>
Total Inertia constant (H)		
at 1200 rpm	4.55	s
at 1440 rpm	6.55	s

**Minimum Required Wind Plant Response to Emergency Low Voltage**



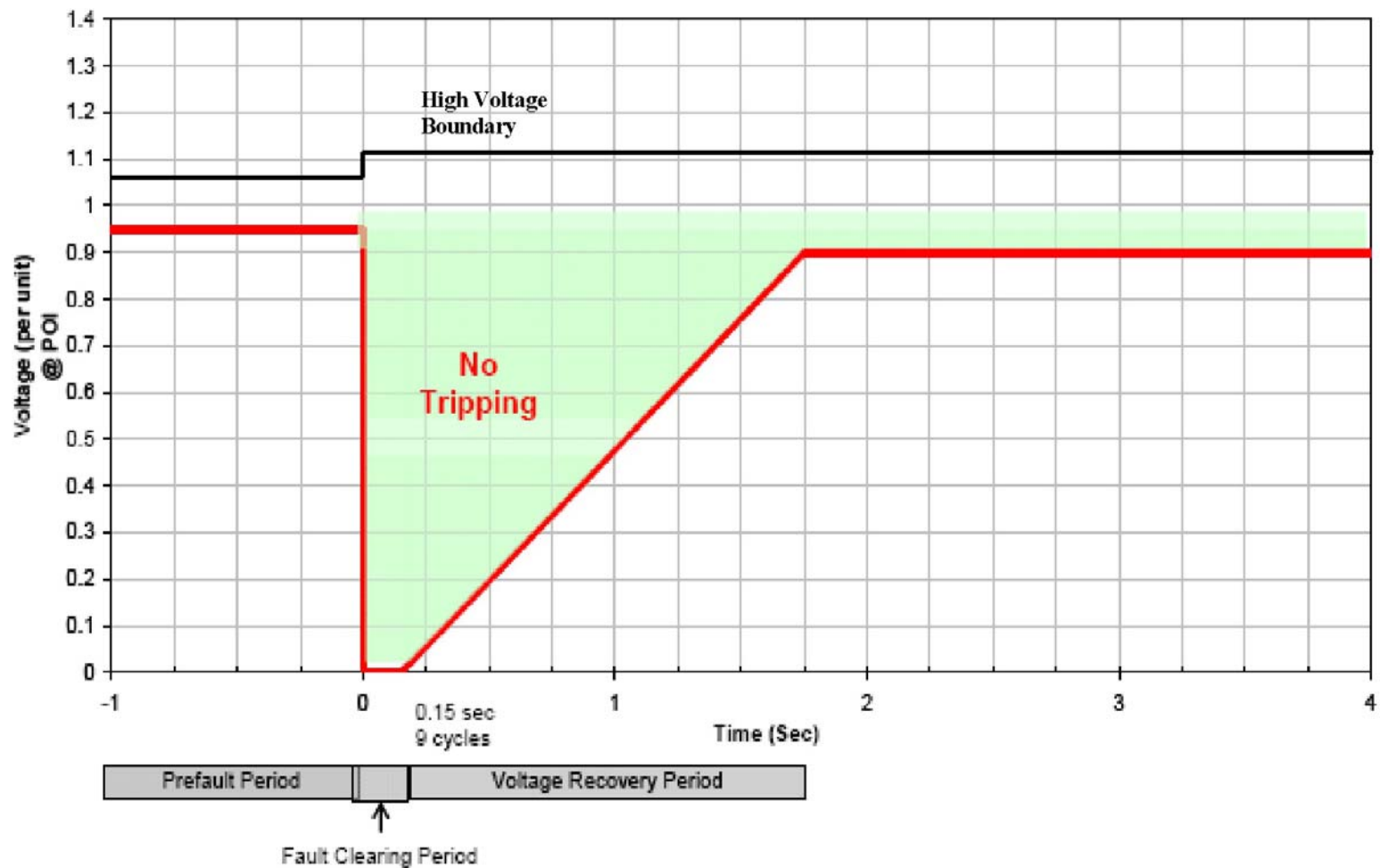
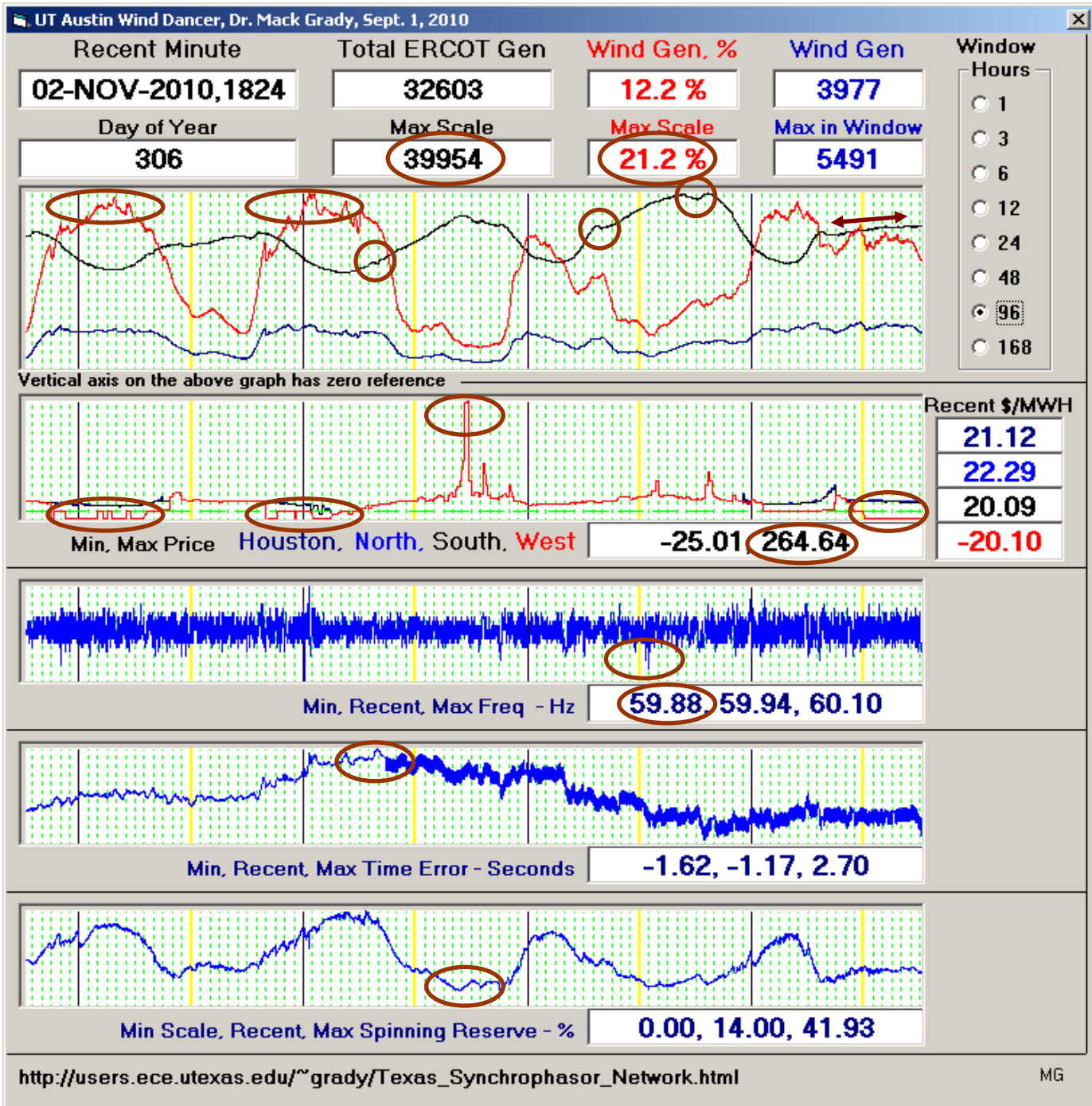


Figure 1: Voltage Ride-Through Boundaries For Wind-powered Generation Resources

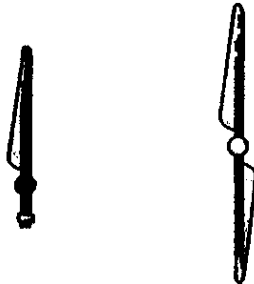


Each Annotation Falls Into a Category

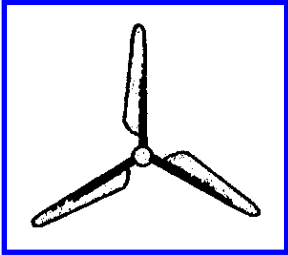
- Wind gen artificially held back
- Not enough gen – makes some money
- Significant unit trip
- Winter started
- Rush hour
- Not rush hour
- How big compared to summer peak?
- Wind gen in phase with load
- Clocks approaching correction tolerance limit
- Wind gen too high

**Blue font and lines – need to know**

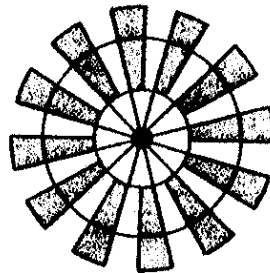
**Horizontal axis turbines**



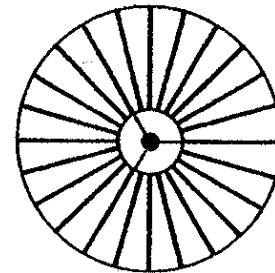
Single bladed  
Double bladed



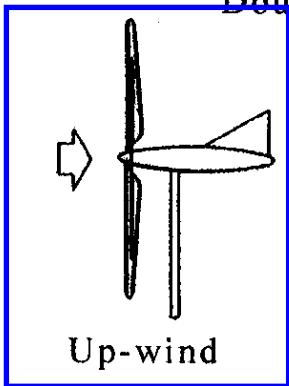
Three-bladed



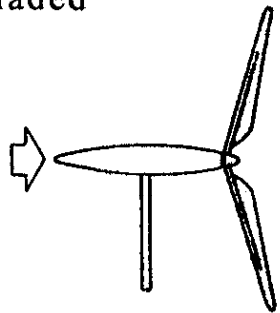
U.S. farm windmill  
multi-bladed



Bicycle  
multi-bladed



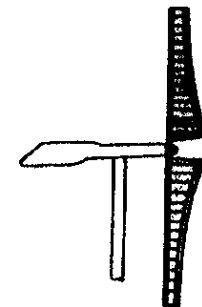
Up-wind



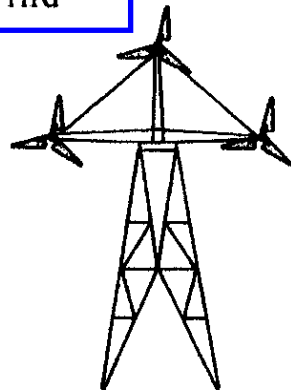
Down-wind



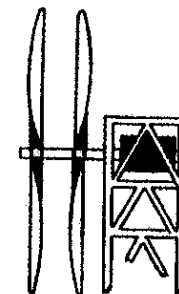
Enfield - Andreau



Sail wing



Multi-rotor



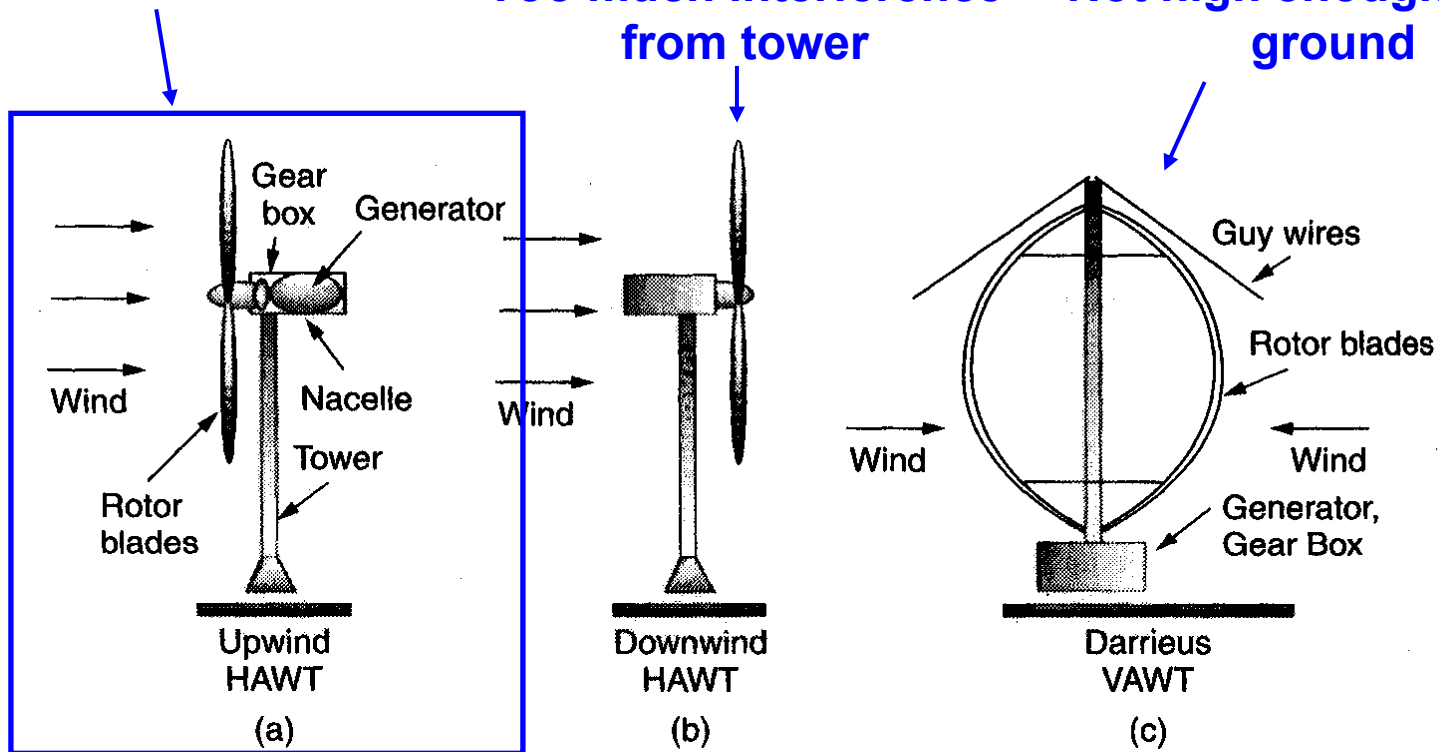
Counter-rotating blades

**These are all lift-type (the sweep surface faces the wind)**

These are suitable for utility-scale generation

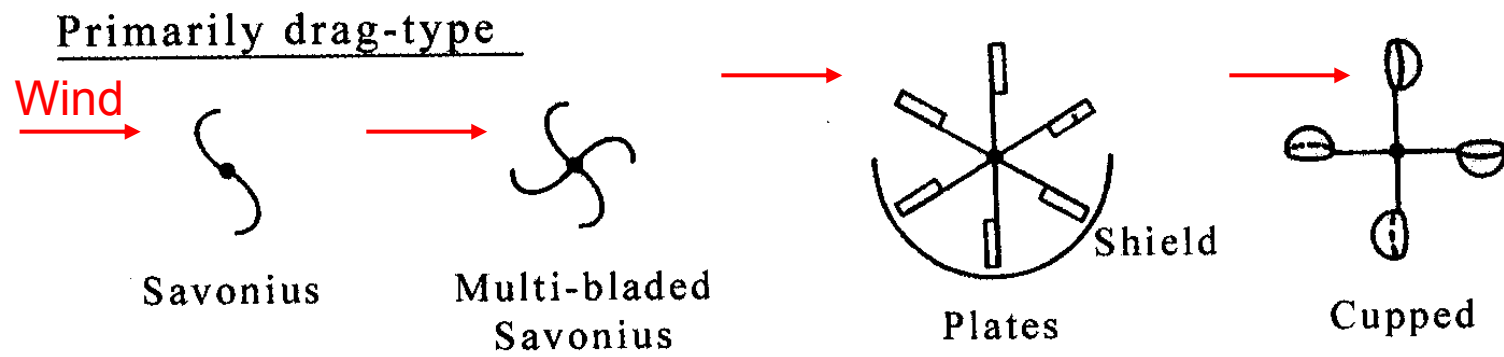
Too much interference from tower

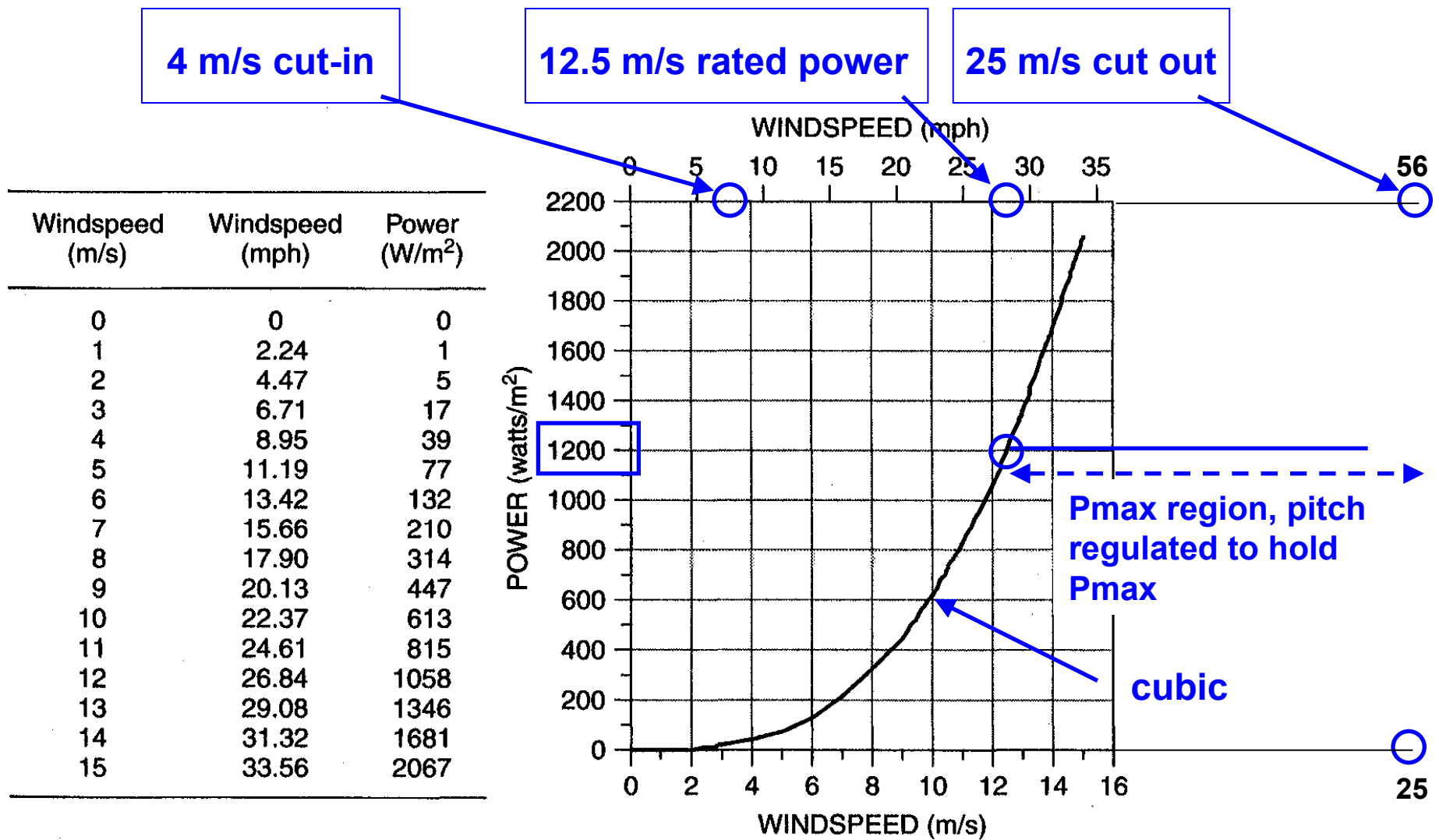
Not high enough above ground



**Figure 6.4** Horizontal axis wind turbines (HAWT) are either upwind machines (a) or downwind machines (b). Vertical axis wind turbines (VAWT) accept the wind from any direction (c).

## Drag-Type - not suitable for serious power



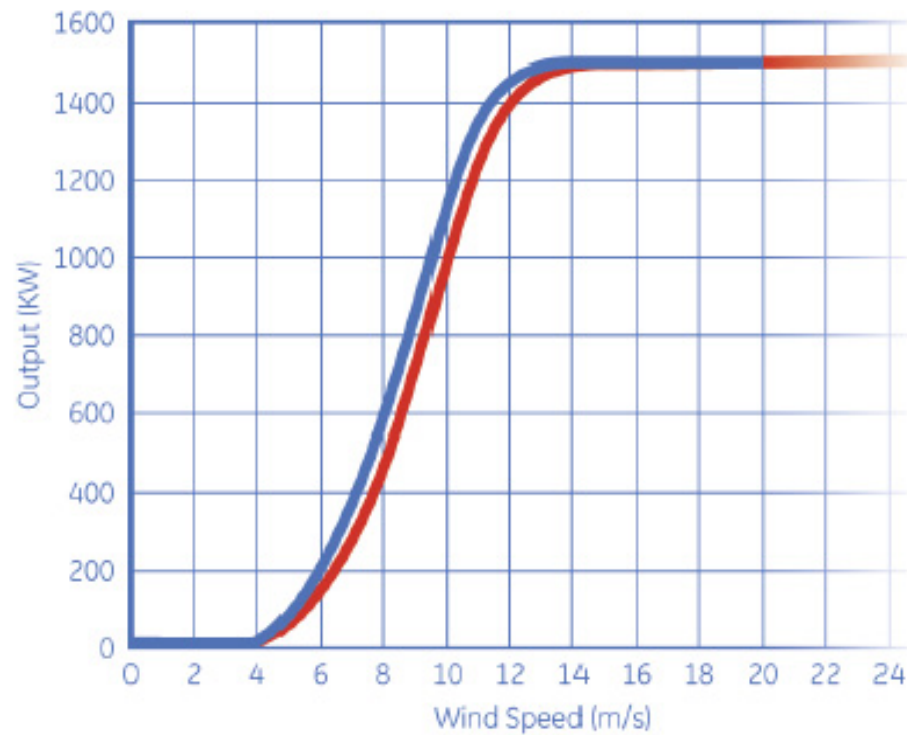


**Figure 6.5** Power in the wind, per square meter of cross section, at 15°C and 1 atm.

**1 mile = 1609 m**

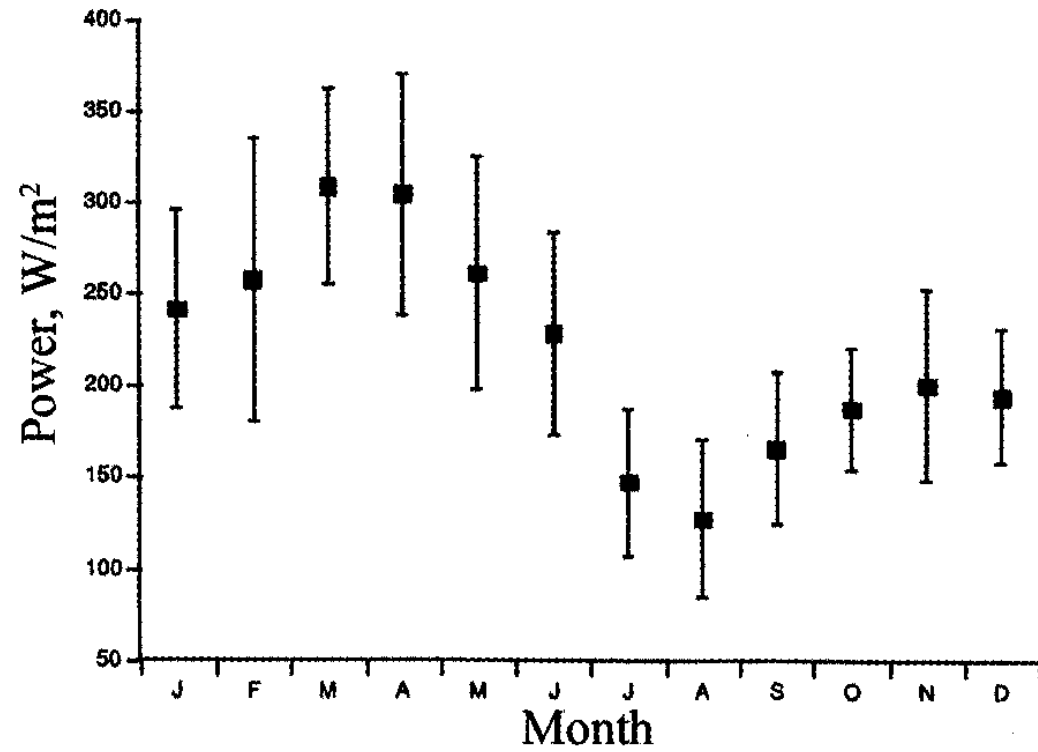


# Power Curve



GE 1.5xl

GE 1.5sl



**Figure 2.7** Seasonal variation of available wind power per unit area for Amarillo, Texas (Rohatgi and Nelson, 1994). Reproduced by permission of Alternative Energy Institute

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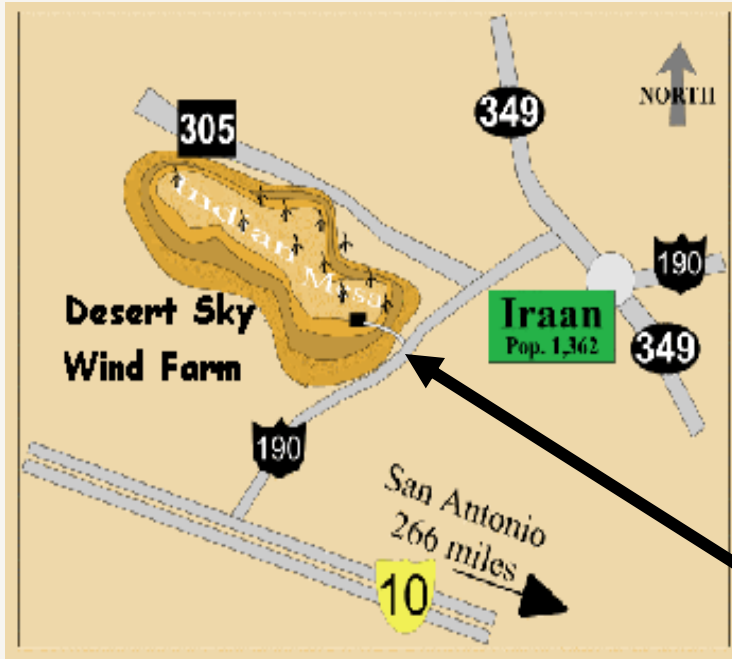
# Desert Sky Wind Farm



[www.desertskywind.com](http://www.desertskywind.com)



# Desert Sky Wind Farm - Map



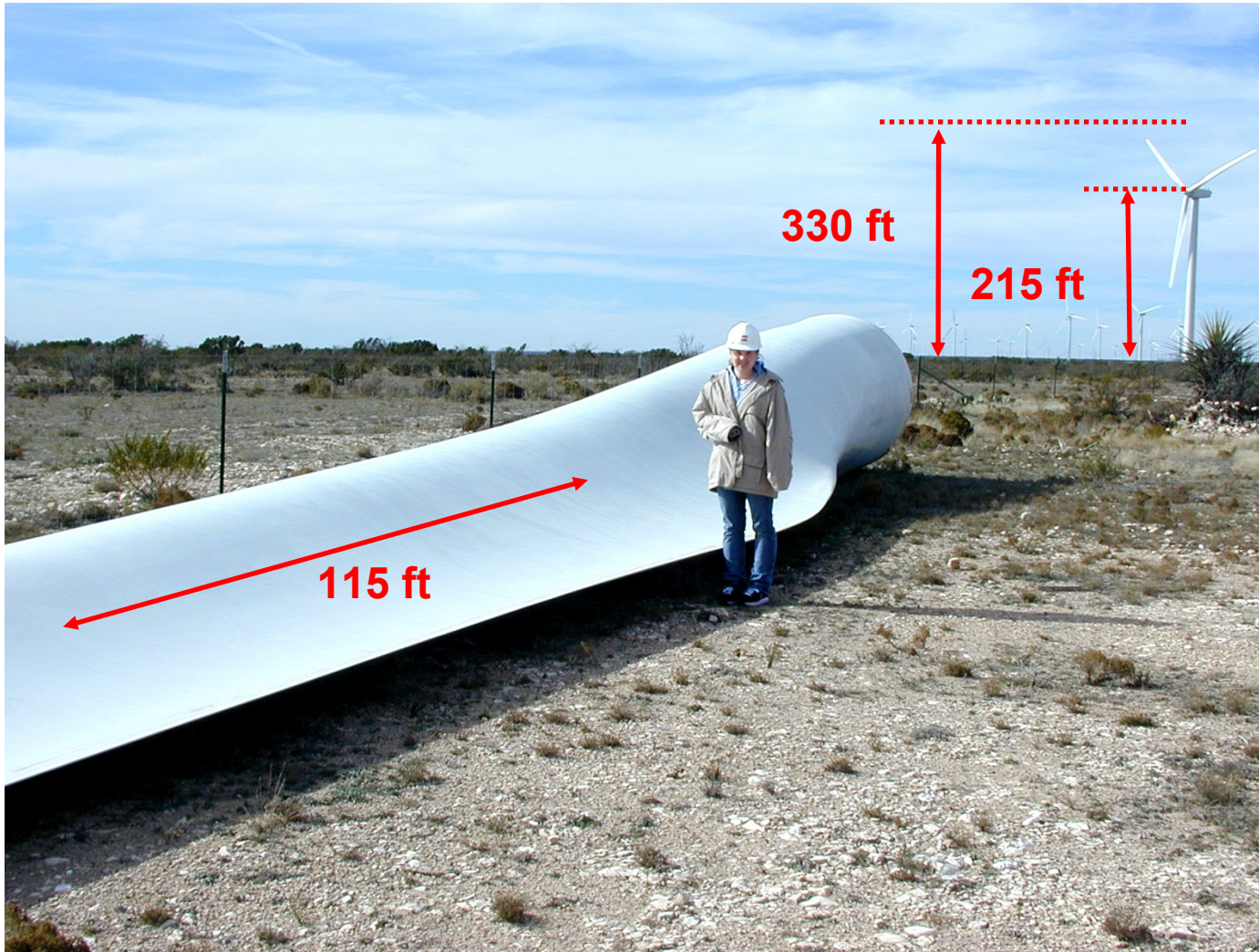
- Dallas - 400 Miles
- San Antonio - 266 Miles
- Odessa - 90 Miles

- Ft. Stockton - 50 miles
- McCamey - 20 Miles
- Iraan - 12 Miles



May 2003

# Desert Sky Wind Farm (approx 300 miles due west of Austin)



At least 100 wind turbines in a wind farm

Approx. 10 wind turbines (15 MW) per square mile. Thus, a farm needs at least 10 square miles.

Metric units – about 6 MW per square km.

Operate at 10 – 20 RPM, with wind speed range 8 – 56 MPH

# Desert Sky Wind Farm

---

- **Commercial operation - Jan '02**
- **160 MW Project**
  - One hundred seven 1.5 MW **turbines**
  - 211 ft (65 meter) hub height
  - 229 ft (70.5 meter) rotor diameter
  - Total height of 329 ft (101 meters) to top of blade tip to base
- **Project occupies about 16 square miles**
- **One substation with two transmission interconnects**



May 2003

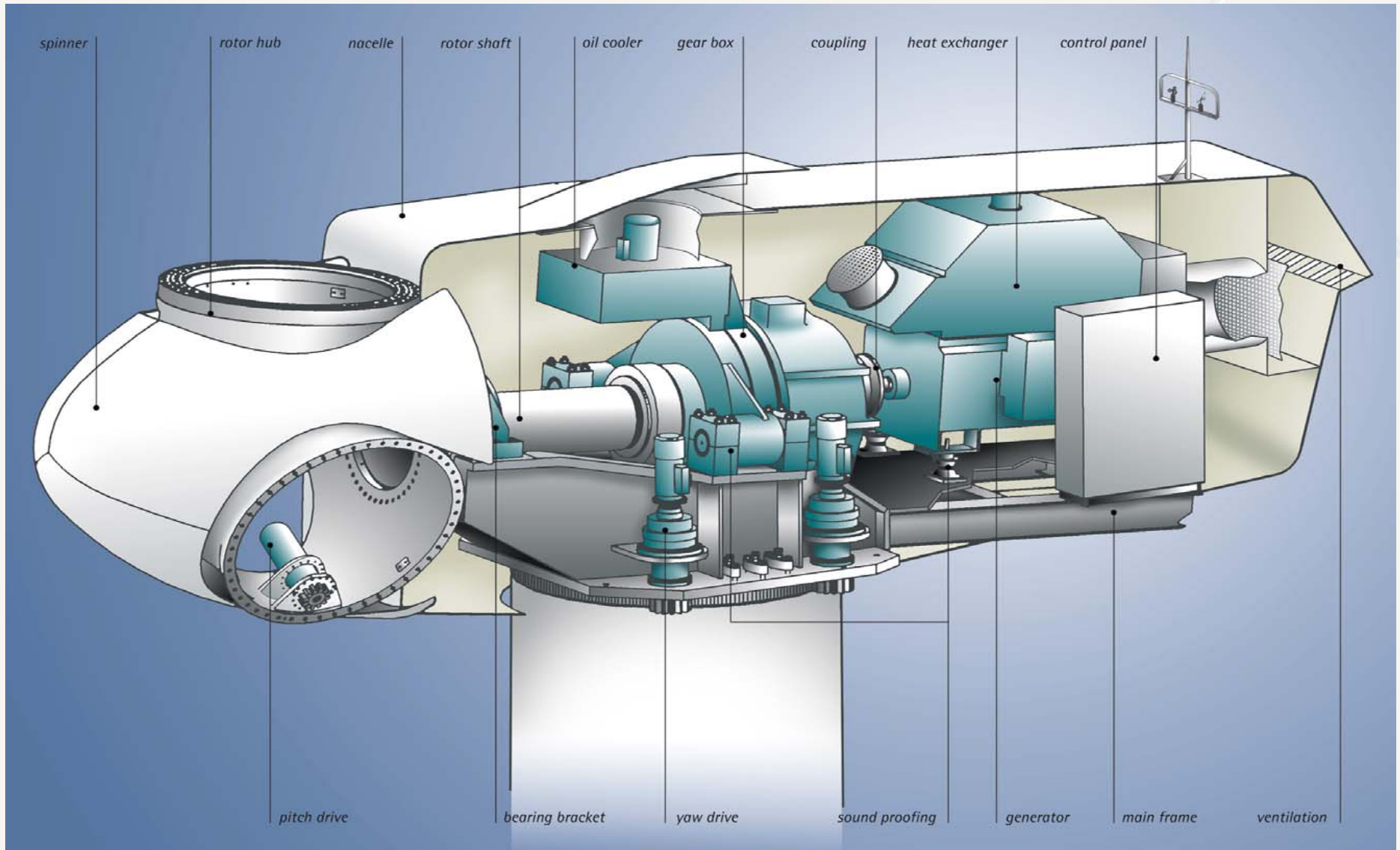
# GE 1.5S Wind **Turbine** Operation

---

- Operates in 8-56 mph wind speeds
- Each **turbine** is a self-contained independent power plant, no operator intervention required
- Onboard weather station, yaw control facing wind
- Variable speed, operates from 10-20 RPM rotor/blade assembly, generator speeds 850 to 1440 RPM



# Nacelle Layout





# Technical Talking Points

---

**\*6 pole machine, Synchronous speed 1200 rpm.**

**\*Converter operation (Variable speed machines), Sub-synchronous/super-synchronous operation**

**\*Gearbox Operation (1:72 ratio)**

**\*Low Voltage ride through**

**\*Collection system/substation design**

**\*Transmission system issues (congestion)**

**\*Power Factor/ VAR control/Transmission system voltage control**

**\*Non-dispatchable nature of wind power/renewable energy systems in general**

**\*Climb assists**

May 2003

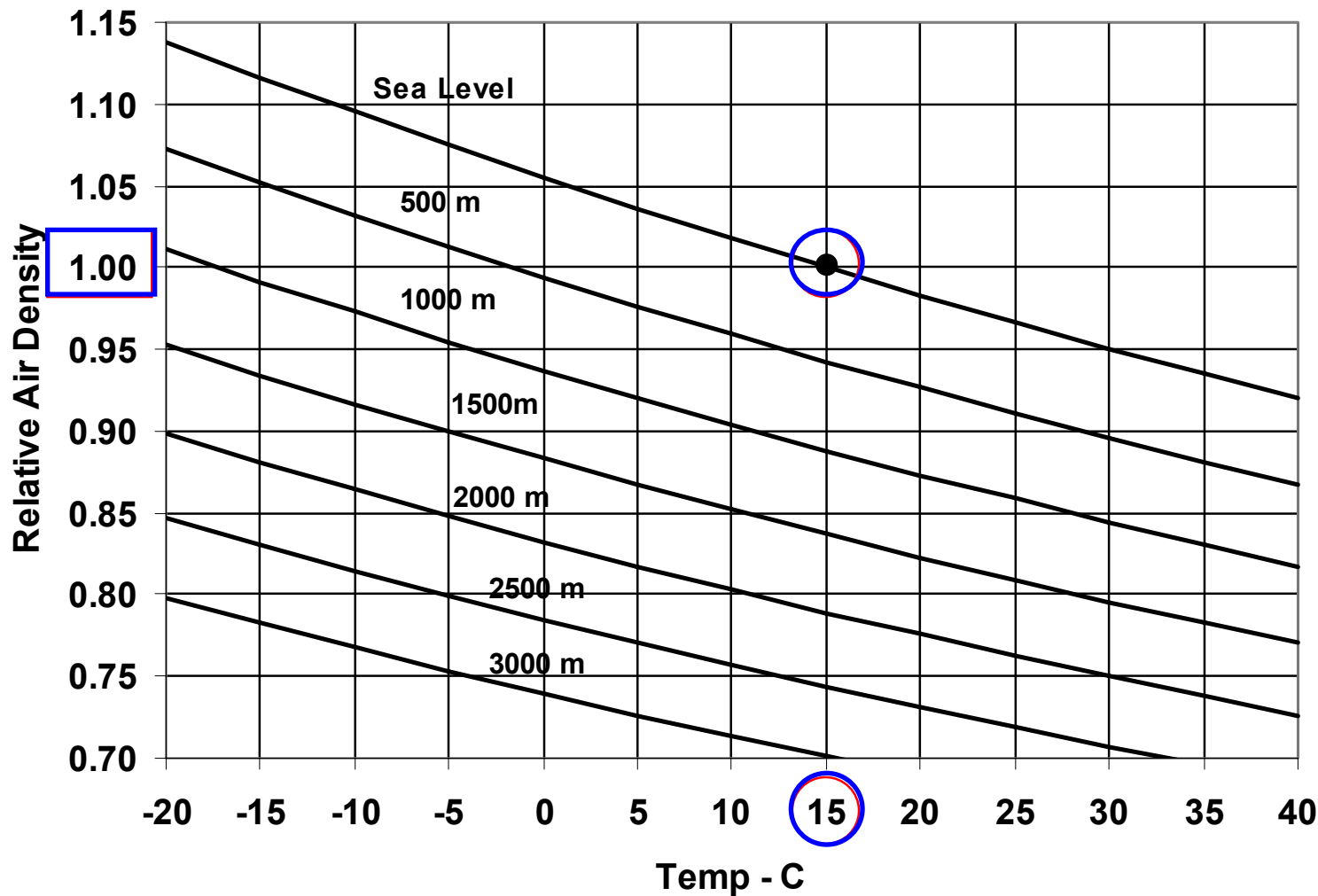
# O&M - Non-Routine Corrective Maintenance

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- **Blade repairs, lightning damage & leading edge erosion.**
  - Blade inspections and repairs are completed annually.
  - About 25 lightning related repairs per year.  
**25 lightning-related repairs per year per 100 turbines**
  - Since commissioning, three blades have required replacement due to lightning damage.
- **Gearbox failures and subsequent replacement.**
  - **Gearbox life cycle appears to be 5-8 years.**

**Note: The repairs mentioned above require two cranes, a large 300 ton crane and a smaller 100 ton crane. Crane availability and expense are serious issues facing wind farm owners. Demand for crane service is currently outpacing availability.**

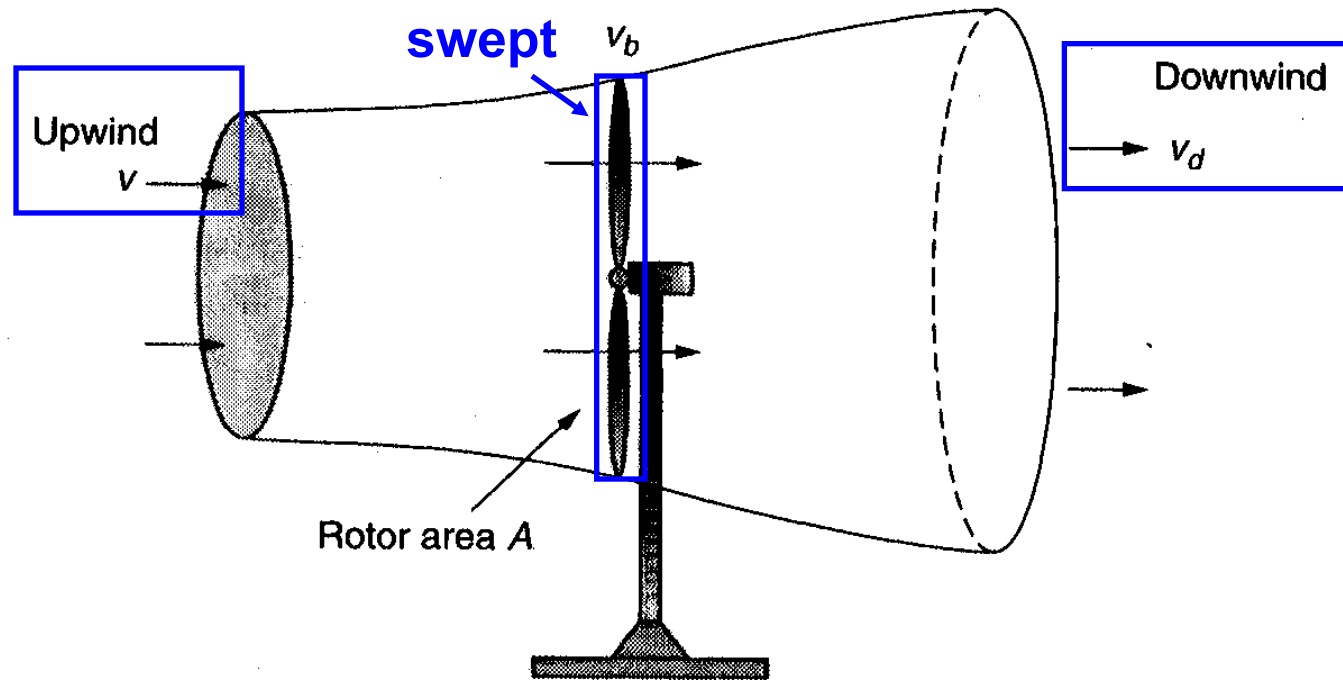
Relative Air Density (**Nominal** 1.0 at Sea Level, 15 Deg C)



Drops about  
0.1 per  
1000m,  
and about  
0.1 per 15° C

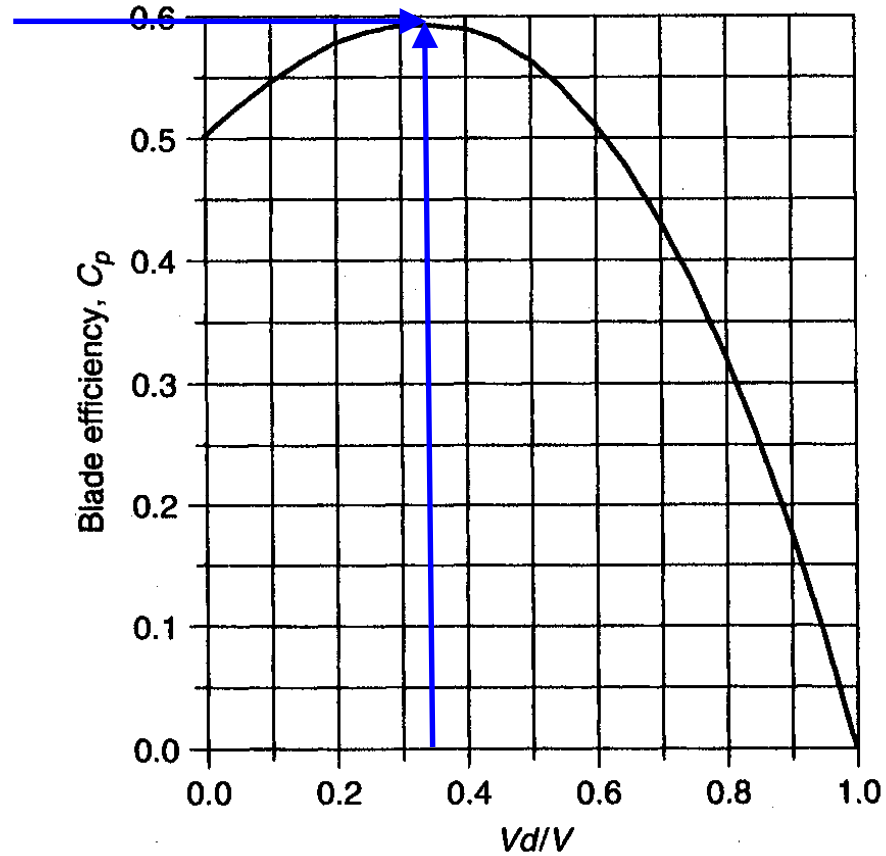


**Betz Limit – Max theoretical turbine energy capture = 59.3% of swept area when downwind is slowed to 1/3<sup>rd</sup> of the upwind speed.**

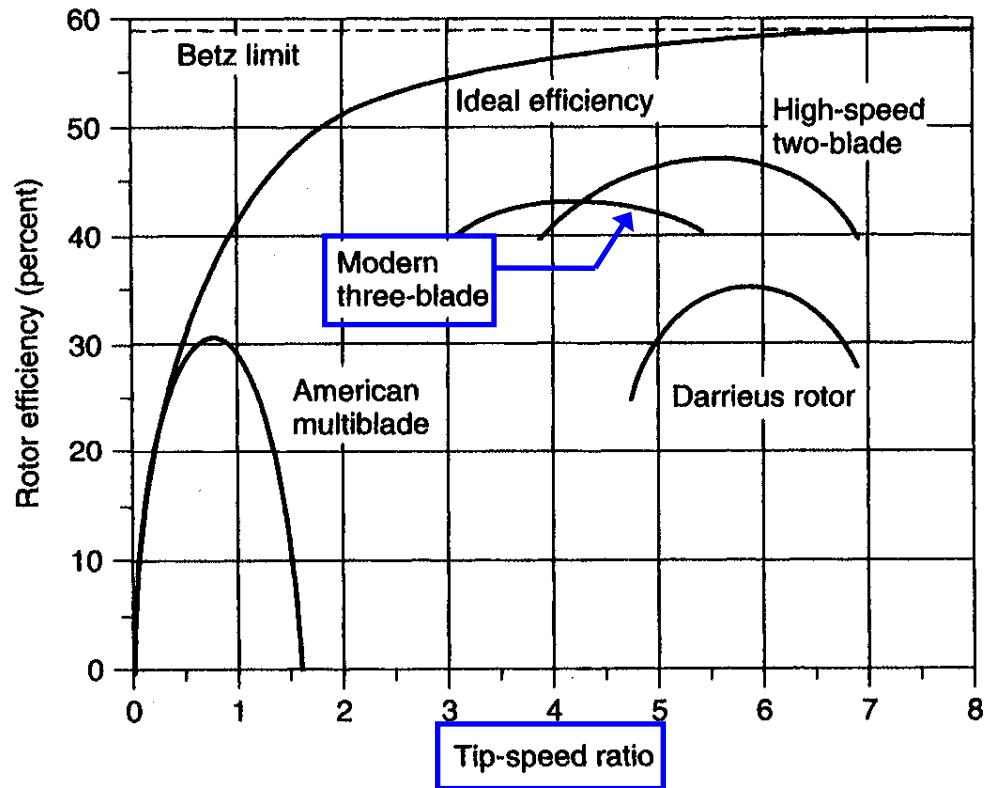


**Figure 6.9** Approaching wind slows and expands as a portion of its kinetic energy is extracted by the wind turbine, forming the stream tube shown.

Betz Limit – Max theoretical turbine energy capture = 59.3% of swept area when downwind is slowed to 1/3rd of the upwind speed.



**Figure 6.10** The blade efficiency reaches a maximum when the wind is slowed to one-third of its upstream value.



**Figure 6.11** Rotors with fewer blades reach their optimum efficiency at higher rotational speeds.

$$TSR = \frac{\text{Tip Speed}}{v_{wind}} = \frac{\omega_{rotor} (\text{rad} / \text{sec}) \bullet R_{rotor} (m)}{v_{wind} (m / \text{sec})}$$

# Response from Roy Blackshear, Manager of Desert Sky Wind Farm

- We reach rated power at about 12.5 m/s or 28 mph at an air density of 1.09, which was originally calculated as the year round average for this site.
- When wind speeds exceed rated, i.e., >12.5 m/s, the blades pitch-regulate to maintain rated output and rotor speed at slightly over 20 rpm.
- **Turbines** pitch blades out of the wind if 10 minute average wind speeds exceed 25 m/s or 56 mph, or wind speeds of > 28 m/s for 30 seconds, or storm gusts of 30 m/s or 67 mph.

## **Roy Blackshear, cont.**

- Lower ambient temperatures in the winter increase the air density substantially, resulting in improved performance of about 5% on the coldest days.
- In general, the change in performance is subtle and only apparent where ambient temperatures are very low, below freezing.



## From GE Wind Energy Basics

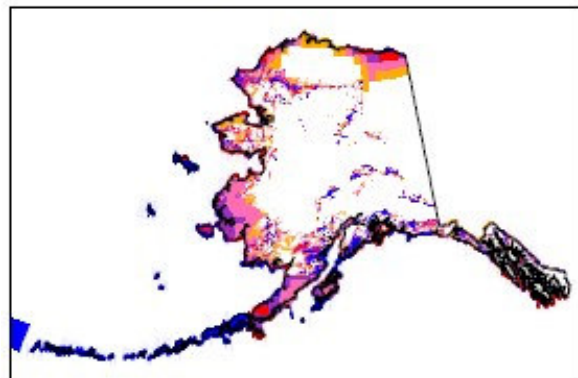
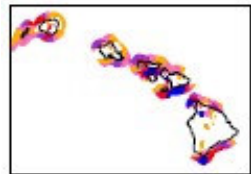
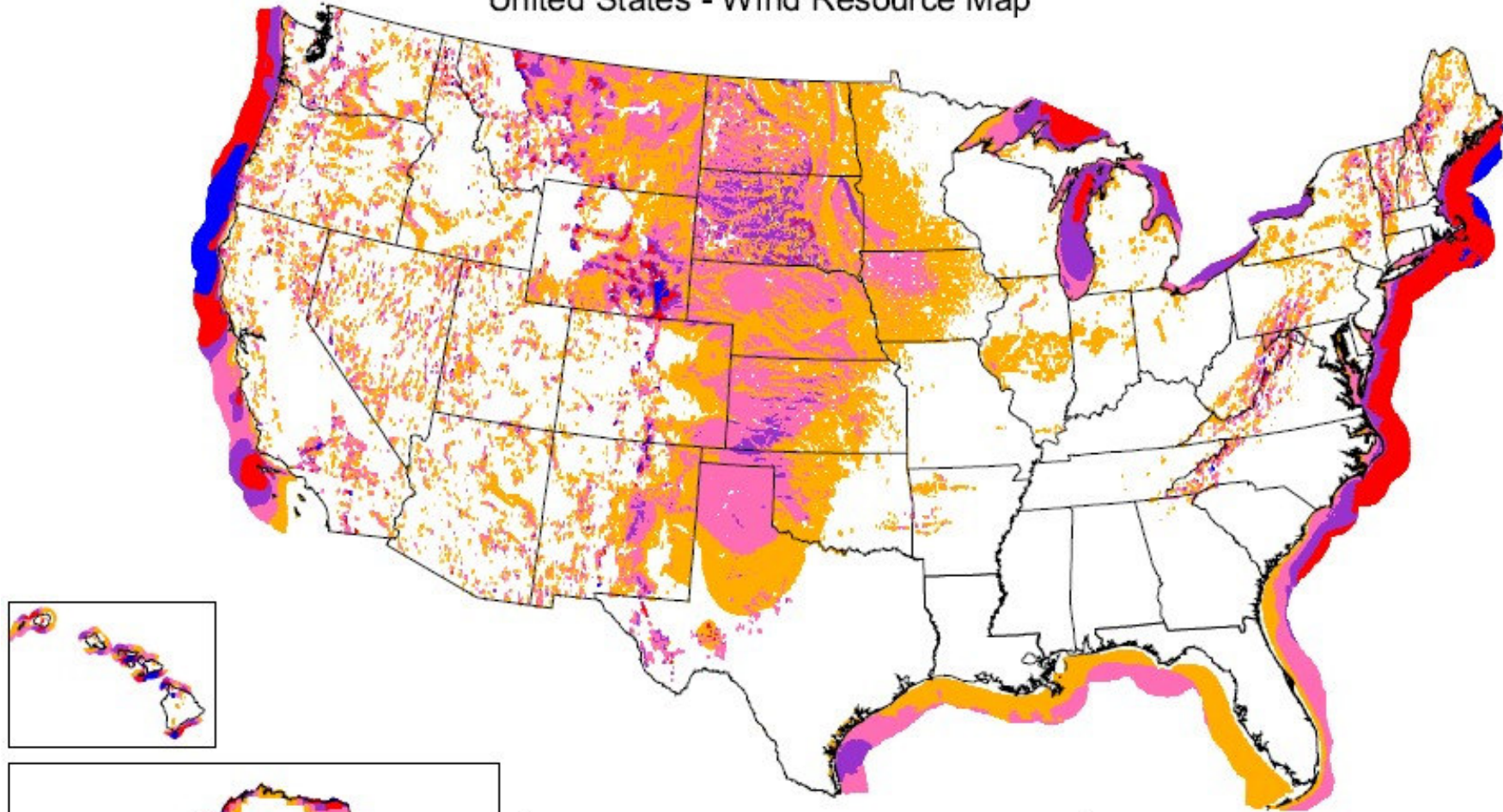
**Q. How much does a wind farm cost?**

**A. The total cost will vary significantly based on site-specific conditions, permitting and construction requirements, and transportation constraints. In general wind power development can cost around **\$2 million per megawatt (MW) of generating capacity installed**, including supporting infrastructure commonly referred to as Balance of Plant (BoP).**

**Q. How big are wind turbines?**

**A. The “tip height” of a GE 1.5 MW turbine is approximately 120 meters, which represents the total height of tower plus a blade in its highest vertical position.**

# United States - Wind Resource Map



Wind Power Classification				
Wind Power Class	Resource Potential	Wind Power Density at 50 m $W/m^2$	Wind Speed <sup>a</sup> at 50 m m/s	Wind Speed <sup>a</sup> at 50 m mph
3	Fair	300 - 400	6.4 - 7.0	14.3 - 15.7
4	Good	400 - 500	7.0 - 7.5	15.7 - 16.8
5	Excellent	500 - 600	7.5 - 8.0	16.8 - 17.9
6	Outstanding	600 - 800	8.0 - 8.8	17.9 - 19.7
7	Superb	800 - 1600	8.8 - 11.1	19.7 - 24.8

<sup>a</sup> Wind speeds are based on a Weibull k value of 2.0

**Moderate: 6.4 - 7 m/s**

**Good: 7 - 7.5 m/s**

**Excellent: >7.5 m/s**



U.S. Department of Energy  
National Renewable Energy Laboratory

## **Wind Energy's Potential**

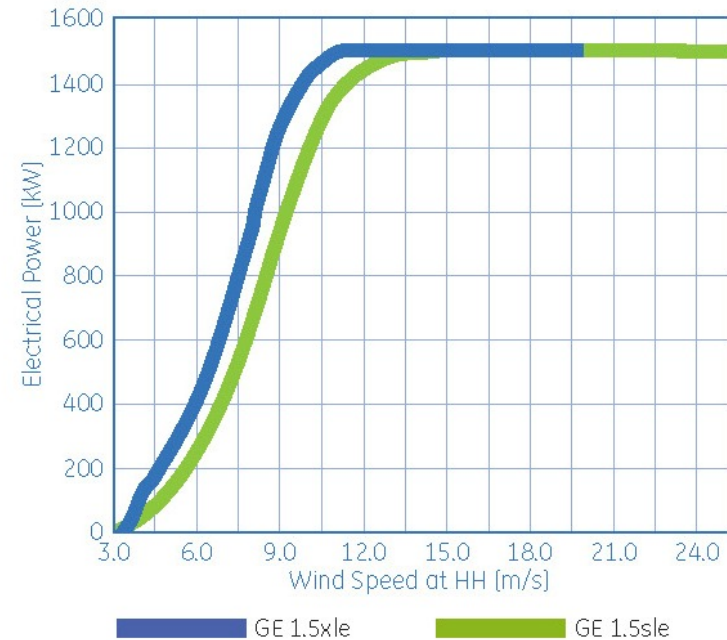
- Wind power accounted for about 42% of all new power generating capacity added in the US in 2008, representing one of the largest components of new capacity addition.**
- Wind energy could supply about 20% of America's electricity, according to Battelle Pacific Northwest Laboratory, a federal research lab. Wind energy resources useful for generating electricity can be found in nearly every state.**
- Wind is projected to deliver 33% of all new electricity generation capacity and provide electricity for 86 million Europeans by 2010.**

# GE 1.5MW Turbines

## Technical data

	1.5sle	1.5xle
<b>Operating Data</b>		
Rated Capacity:	1,500 kW	1,500 kW
Temperature Range: (with Cold Weather Extreme Package)	Operation: -30°C - +40°C Survival: -40°C - +50°C	-30°C - +40°C -40°C - +50°C
Cut-in Wind Speed:	3.5 m/s	3.5 m/s
Cut-out Wind Speed (10 min avg):	25 m/s	20 m/s
Rated Wind Speed:	14 m/s	11.5 m/s
Wind Class – IEC:	IIa ( $V_{e50} = 55$ m/s $V_{ave} = 8.5$ m/s)	IIIb ( $V_{e50} = 52.5$ m/s $V_{ave} = 8.0$ m/s)
<b>Electrical Interface</b>		
Frequency	50/60 Hz	50/60 Hz
Voltage	690V	690V
<b>Rotor</b>		
Rotor Diameter:	77 m	82.5 m
Swept Area:	4657 m <sup>2</sup>	5346 m <sup>2</sup>
<b>Tower</b>		
Hub Heights:	65/80 m	80 m
<b>Power Control</b>		
	Active Blade Pitch Control	Active Blade Pitch Control

## Power curve



**1.5sle** – Classic workhorse, an efficient and reliable machine with proven technology

**1.5xle** – Built on the success of the 1.5sle platform, captures more wind energy with 15% greater swept area

# MITSUBISHI WIND TURBINE GENERATOR

# MWWT 102/2.4



## Technical Data

---

### Operation Data

Cut-in	3.0 m/s
Rated	11.5 m/s
Cut-out	25.0 m/s
Wind Class	IEC Class IIA

### Rotor

Diameter	102 m
Swept Area	8,171 m <sup>2</sup>
Rotational Speed (rated)	15.0 rpm
Rotational Speed (interval)	9.0 ~ 16.9 rpm (variable)
Blade Length	49.7 m
Aerodynamic Brake	Individual Pitch Brake

### Generator

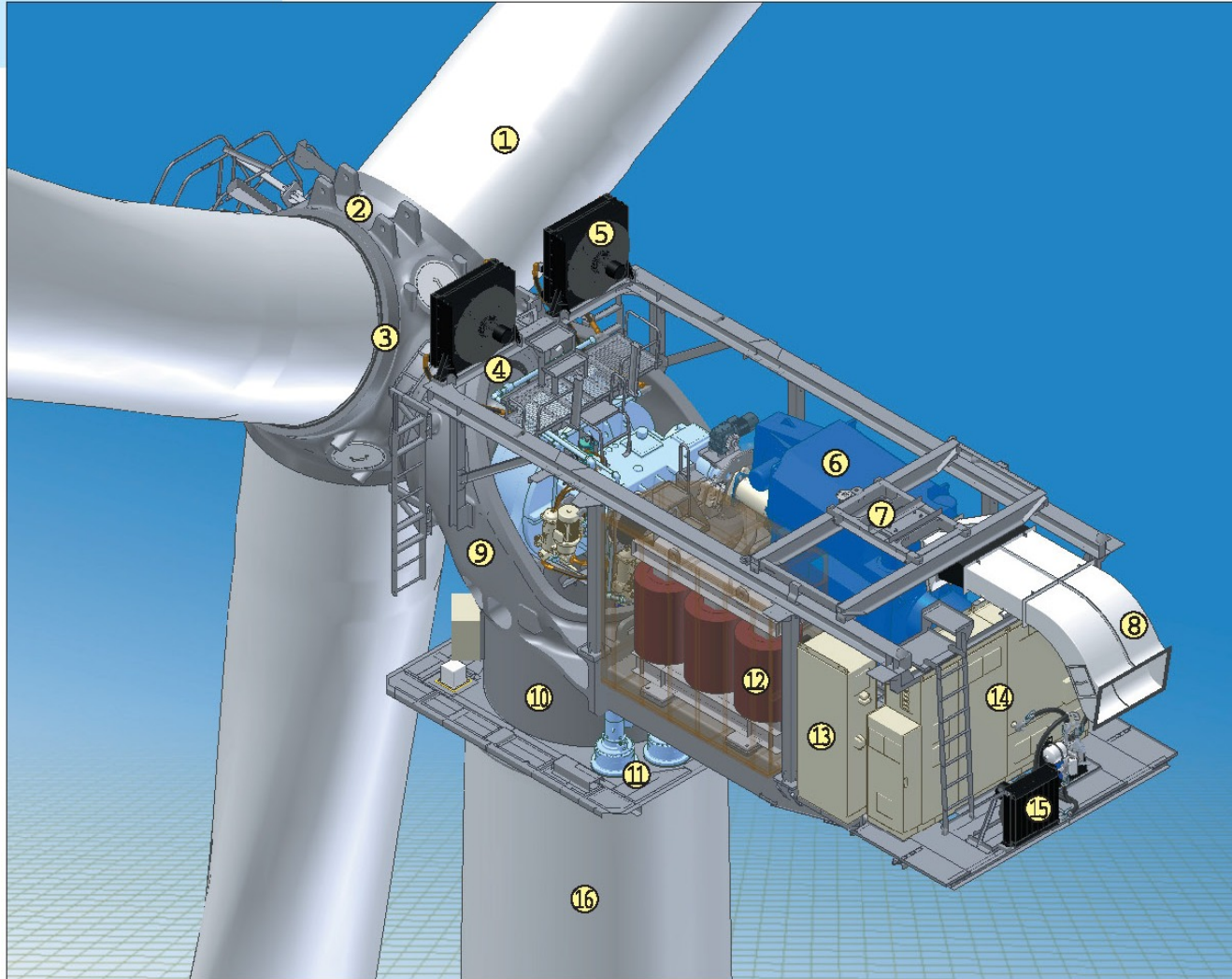
Type	Doubly Fed Asynchronous Generator + IGBT Converter
Rated Power	2,400 kW
Voltage	690 V
Frequency	50 Hz/60 Hz
Power Factor Range	0.9 (inductive) ~ 0.95 (capacitive)

### Tower

Hub Height	80 m
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- High performance in moderate wind speed area (IEC Class IIA)
- Individual pitch control



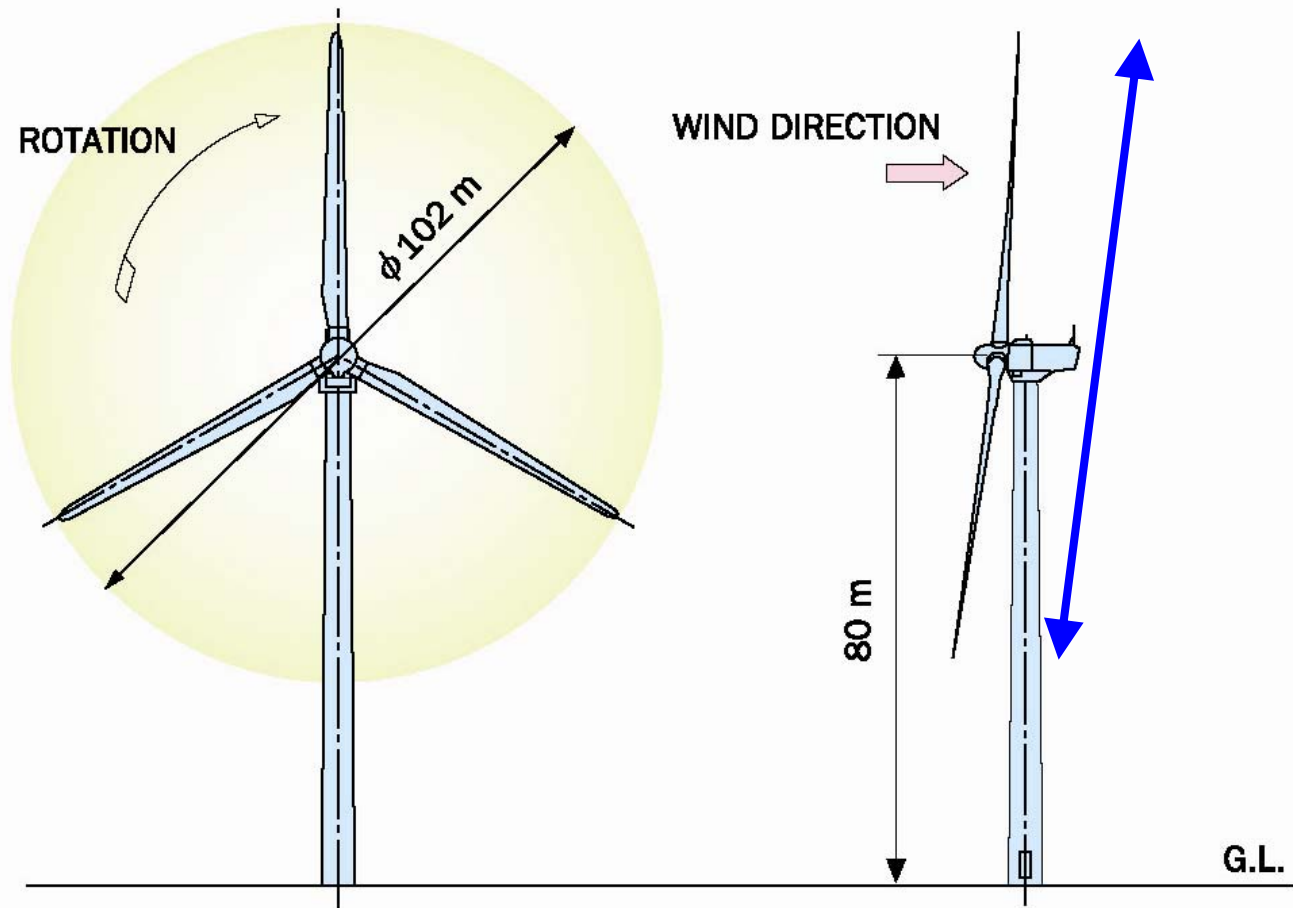
### Schematic Diagram

- |                 |                              |                     |                       |
|-----------------|------------------------------|---------------------|-----------------------|
| ① Blade         | ⑤ Oil Cooler                 | ⑨ Nacelle Bed Plate | ⑬ Control Panel       |
| ② Hub           | ⑥ Generator                  | ⑩ Yaw Bearing       | ⑭ Inverter            |
| ③ Blade Bearing | ⑦ Service Winch              | ⑪ Yaw Gear          | ⑮ Cooler for Inverter |
| ④ Main Bearing  | ⑧ Exhaust Duct for Generator | ⑫ Transformer       | ⑯ Tower               |

# Tower

Hub Height

80 m



## EE411, Fall 2011, Lab. 4. Phase-Locked Loop

In Lab 1, you manually followed the 120Vac grid voltage by adjusting an external waveform generator. In Lab 4, you will perform the same feat using your built-in pulse generator, and also automate the process using a phase-locked loop with proportional-integral (PI) controller. A phase-locked loop “locks” the phase and frequency of the built-in pulse generator with the 120Vac voltage.

In Lab 1, you used the following cosine product trig expression:

$$\cos(\omega_1 t + A) \bullet \cos(\omega_2 t + B) = \frac{1}{2} [\cos\{(\omega_1 - \omega_2)t + A - B\} + \cos\{(\omega_1 + \omega_2)t + A + B\}]$$

which (see page 13) gives positive error in the first “beat frequency” term when the two signals are in phase, zero error when they are 90° out of phase, and negative error when they are 180° out of phase. In Lab 4, you will use the following sine, cosine product to achieve zero error in the beat frequency term when the two signals are in phase (i.e., “phase locked”). The sine term is obtained by integrating the grid voltage.

$$\sin(\omega_1 t + A) \bullet \cos(\omega_2 t + B) = \frac{1}{2} [\sin\{(\omega_1 - \omega_2)t + A - B\} + \sin\{(\omega_1 + \omega_2)t + A + B\}]$$

A PI controller converts a first-order response system (such as an RC or RL circuit) to a second-order response system so that error can be quickly minimized. Our “system,” which is essentially the relationship between the RF3 knob and the pulse generator frequency, is not exactly first-order, but nevertheless it can be approximated as such. You will replace RF3 with a MOSFET, which in our case will be a voltage-controlled resistor. A feedback voltage based upon error and integral of error adjusts the pulse generator frequency to achieve “locking.”

Theory follows on the next few slides. This material is taken from EE462L Power Electronics and illustrates how a PI controller regulates the output voltage of a DC-DC converter.



## EE411, Fall 2011, Lab. 4. Phase-Locked Loop, cont.

A proportional-integral controller (i.e., PI) with feedback can take the place of manual adjustment of the switching duty cycle to a DC-DC converter and act much more quickly than is possible “by hand.” Consider the Transformer, DBR, MOSFET Firing Circuit, DC-DC Converter, and Load as “a process” shown below. In the open loop mode that you used last time, you manually adjusted duty cycle voltage  $D_{cont}$ .

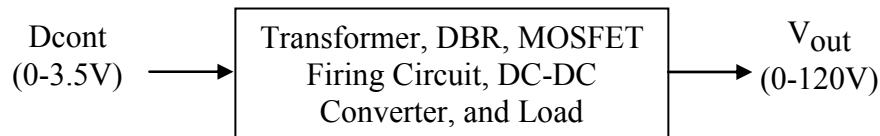


Figure 1. Open Loop Process

To automate the process, the “feedback loop” is closed and an error signal (+ or -) is obtained. The PI controller acts upon the error with parallel proportional and integral responses in an attempt to drive the error to zero.

Let  $\alpha V_{out}$  be a scaled down replica of  $V_{out}$ . When  $\alpha V_{out}$  equals  $V_{set}$ , then the error is zero. A resistor divider attached to  $V_{out}$  produces  $\alpha V_{out}$ , which is suitably low for op-amps voltage levels.

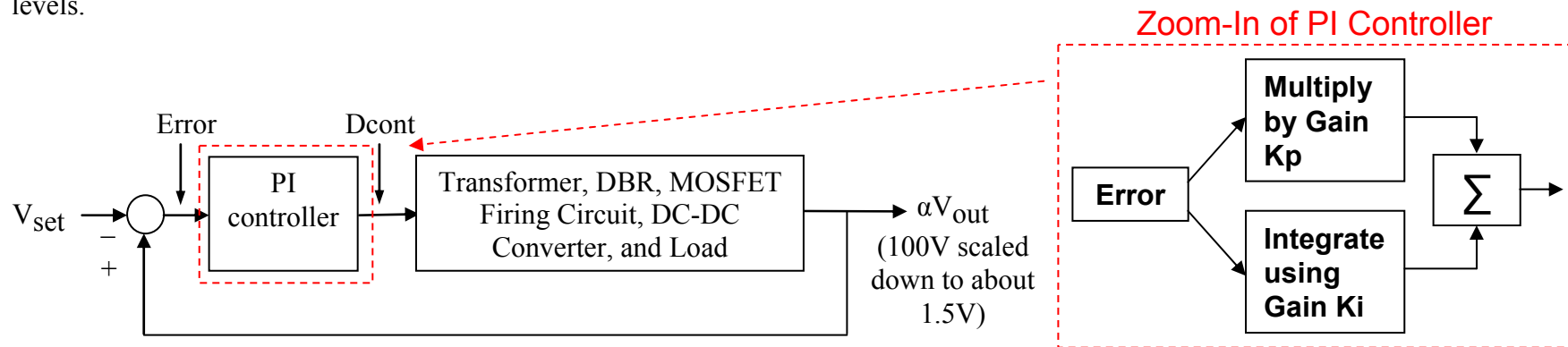
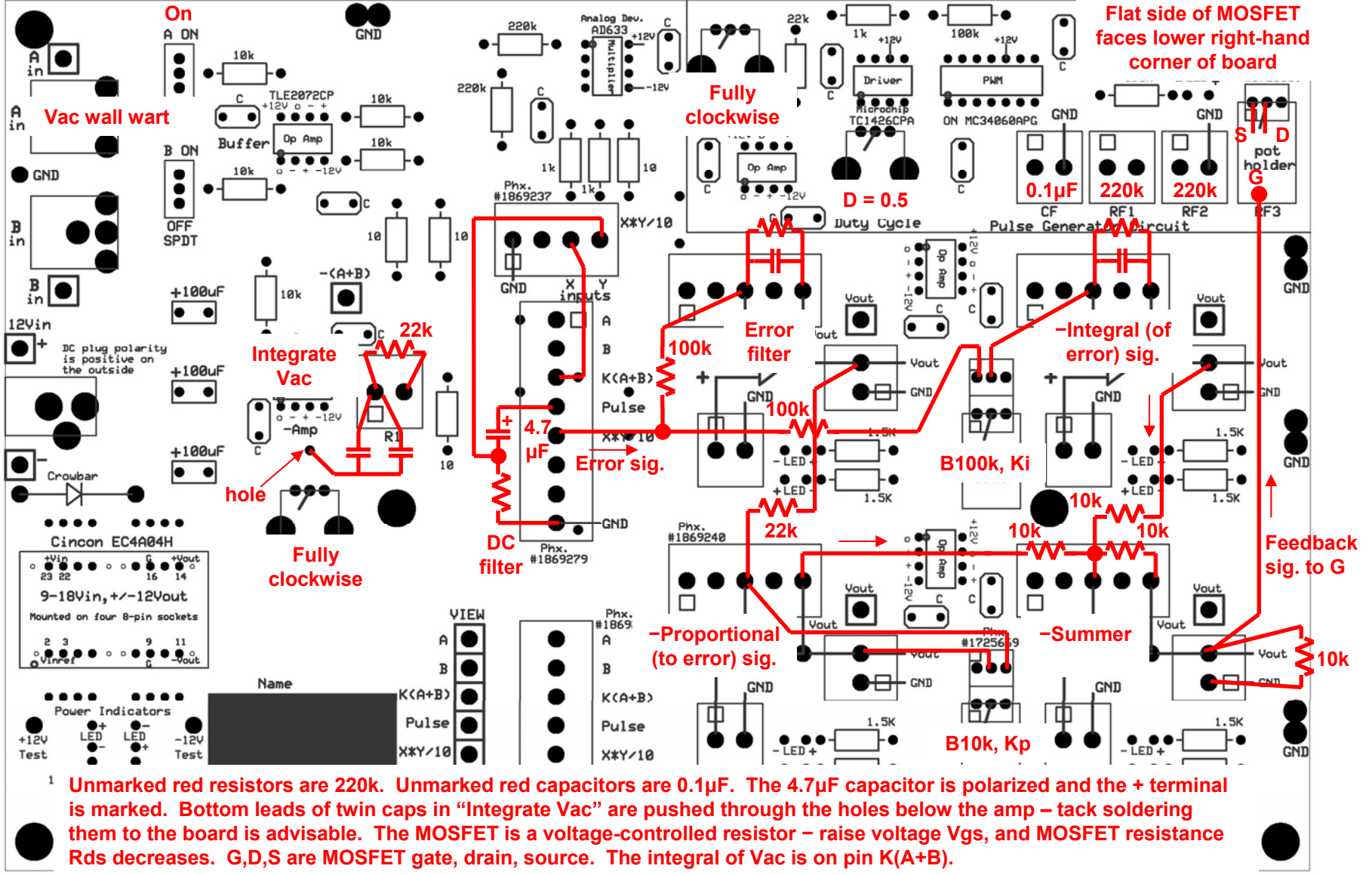


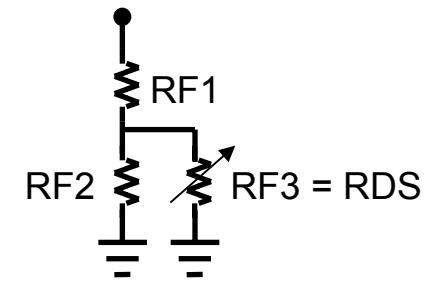
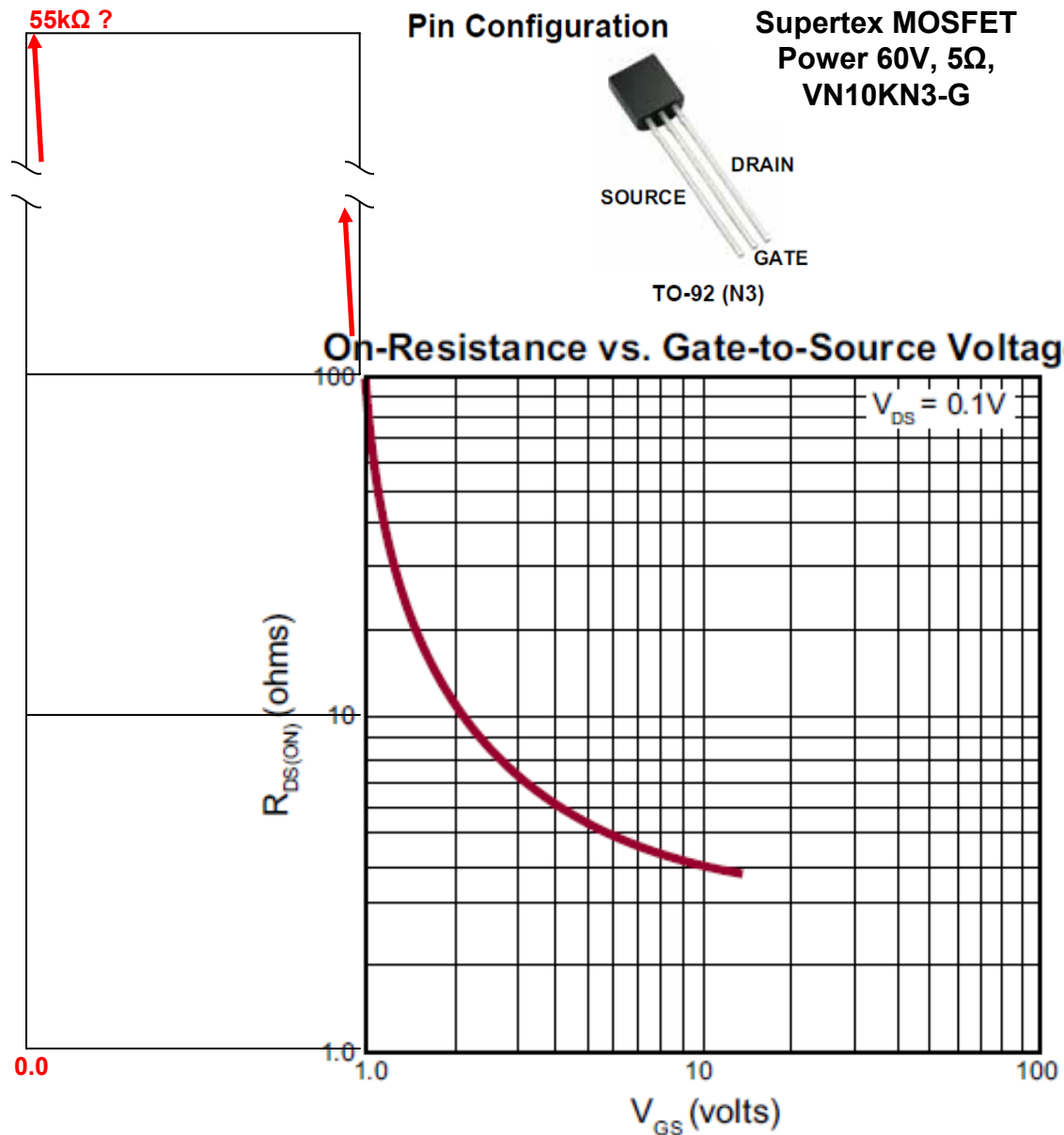
Figure 2. Closed Loop Process with PI Controller

**EE411, Fall 2011, Lab. 4. Phase-Locked Loop, cont.**

**Wire up with #24 solid orange**



EE411, Fall 2011, Lab. 4. Phase-Locked Loop, cont.



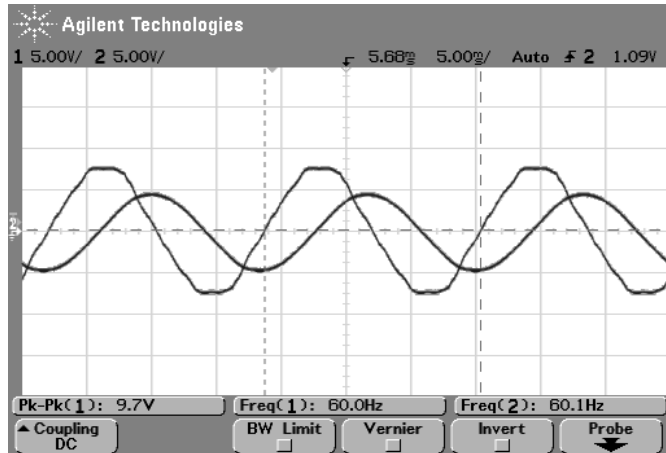
RF for Pulse Generator equals  $RF1 + RF2 \parallel RF3$

Free-Running Tests.  $RF1 = RF2 = 220k\Omega$ ,  $CF = 0.1\mu F$ .

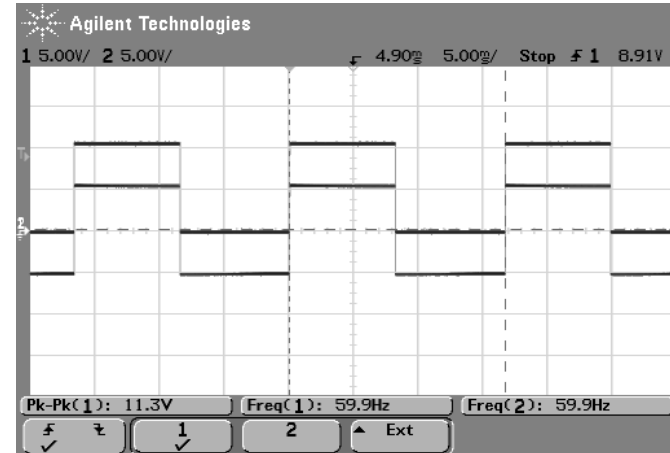
1. When **MOSFET is removed**,  $RF = 440k\Omega$ , and computed  $F = 27Hz$  (**actual measurement is 33Hz**),
2. When  $RF3$  is shorted, which is essentially the same situation as **MOSFET "on,"**  $RF = 220k\Omega$ , and computed  $F = 55Hz$  (**actual measurement is 66Hz**),
3. When **MOSFET is inserted but "off,"** with its open gate terminal connected to ground through a  $1k\Omega$  resistor, the **actual measurement is 55Hz**. Backcalculating,  $RF = 264k\Omega$ , thus **MOSFET "off" resistance is 55kΩ**.
4. You may need to vary  $CF$  or  $RF1$  to achieve a range of frequency similar to the 55-to-66Hz range in Steps 2-3 above. The range should be approx. centered around 60Hz.

# EE411, Fall 2011, Lab. 4. Phase-Locked Loop, cont.

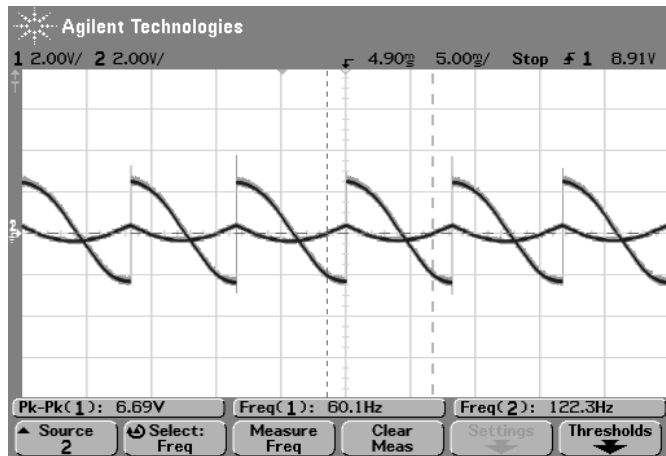
Checkpoint Screen Snapshots, Taken When “Locked”



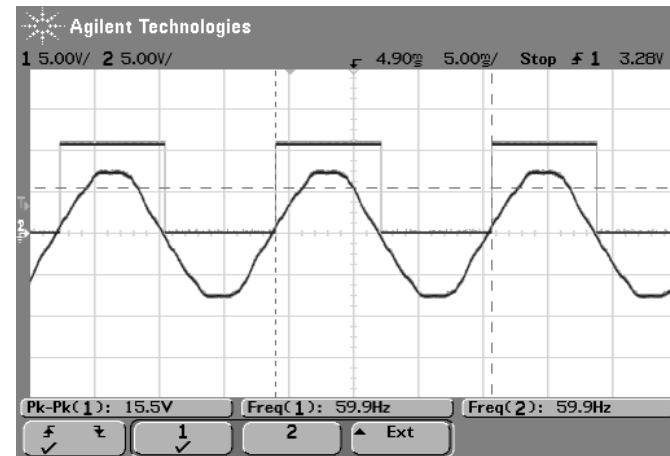
1. Vac (pin A), and integral of Vac (pin K(A+B))



2. Pulse generator (pin PULSE), and pulse generator with DC removed (multiplier input Y)



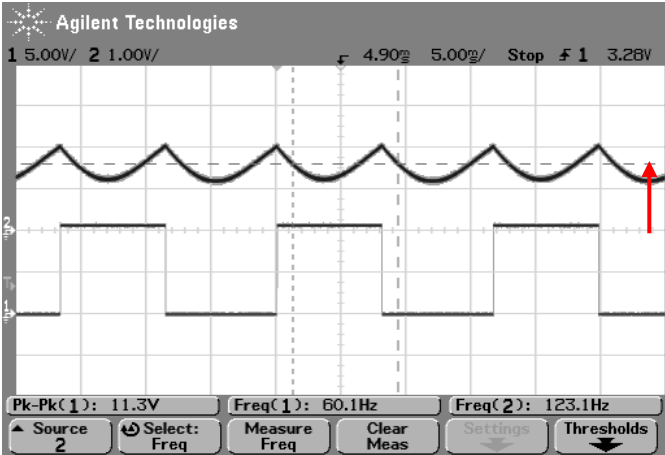
3. Error signal (pin X\*Y/10) and filtered error signal (error filter op amp Vout)



4. Vac (pin A), and pulse generator (pin PULSE). Pulse is steady when locked.



EE411, Fall 2011, Lab. 4. Phase-Locked Loop, cont.



Vgs about 1.5V avg

5. PULSE and MOSFET gate voltage Vgs